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# Entropy and the fourth moment phenomenon 

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#### Abstract

We develop a new method for bounding the relative entropy of a random vector in terms of its Stein factors. Our approach is based on a novel representation for the score function of smoothly perturbed random variables, as well as on the de Bruijn's formula of information theory. When applied to sequences of functionals of a general Gaussian field, our results can be combined with the Carbery-Wright inequality in order to yield multidimensional entropic rates of convergence that coincide, up to a logarithmic factor, with those achievable in smooth distances (such as the 1-Wasserstein distance). In particular, our findings settle the open problem of proving a quantitative version of the multidimensional fourth moment theorem for random vectors having chaotic components, with explicit rates of convergence in total variation that are independent of the order of the associated Wiener chaoses. The results proved in the present paper are outside the scope of other existing techniques, such as for instance the multidimensional Stein's method for normal approximations.


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Keywords: Carbery-Wright inequality; Central limit theorem; de Bruijn's formula; Fisher information; Fourth moment theorem; Gaussian fields; Relative entropy; Stein factors

## Contents

1. Introduction ..... 3171
1.1. Overview and motivation ..... 3171
1.2. Illustration of the method in dimension one ..... 3175
1.3. Plan ..... 3182
2. Entropy bounds via de Bruijn's identity and Stein matrices ..... 3182
2.1. Entropy ..... 3182
2.2. Fisher information and de Bruijn's identity ..... 3183

[^0]2.3. Stein matrices and a key lemma ..... 3187
2.4. A general bound ..... 3189
2.5. A general roadmap for proving quantitative entropic CLTs ..... 3192
3. Gaussian spaces and variational calculus ..... 3193
3.1. Wiener chaos ..... 3193
3.2. The language of Malliavin calculus: chaoses as eigenspaces ..... 3194
3.3. The role of Malliavin and Stein matrices ..... 3197
4. Entropic fourth moment bounds on a Gaussian space ..... 3198
4.1. Main results ..... 3198
4.2. Estimates based on the Carbery-Wright inequalities ..... 3199
4.3. Proof of Theorem 4.1 ..... 3204
4.4. Proof of Corollary 4.2 ..... 3205
Acknowledgments ..... 3205
References ..... 3205

## 1. Introduction

### 1.1. Overview and motivation

The aim of this paper is to develop a new method for controlling the relative entropy of a general random vector with values in $\mathbb{R}^{d}$, and then to apply this technique to settle a number of open questions concerning central limit theorems (CLTs) on a Gaussian space. Our approach is based on a fine analysis of the (multidimensional) de Bruijn's formula, which provides a neat representation of the derivative of the relative entropy (along the Ornstein-Uhlenbeck semigroup) in terms of the Fisher information of some perturbed random vector - see e.g. [1,4,5,21,23]. The main tool developed in this paper (see Theorem 2.10 as well as relation (1.14)) is a new powerful representation of relative entropies in terms of Stein factors. Roughly speaking, Stein factors are random variables verifying a generalized integration by parts formula (see (2.43) below): these objects naturally appear in the context of the multidimensional Stein's method for normal approximations (see e.g. $[15,36]$ ), and implicitly play a crucial role in many probabilistic limit theorems on Gaussian or other spaces (see e.g. [36, Chapter 6], as well as [33,38,41]).

The study of the classical CLT for sums of independent random elements by entropic methods dates back to Linnik's seminal paper [30]. Among the many fundamental contributions to this line of research, we cite [2,3,5,8,22,9,10,12,23] (see the monograph [21] for more details on the history of the theory). All these influential works revolve around a deep analysis of the effect of analytic convolution on the creation of entropy: in this respect, a particularly powerful tool are the 'entropy jump inequalities' proved and exploited e.g. in [3,5,22,6]. As discussed e.g. in [6], entropy jump inequalities are directly connected with challenging open questions in convex geometry, like for instance the Hyperplane and $K L S$ conjectures. One of the common traits of all the above references is that they develop tools to control the Fisher information and use the aforementioned de Bruijn's formula to translate the bounds so obtained into bounds on the relative entropy.

One of the main motivations of the present paper is to initiate a systematic informationtheoretical analysis of a large class of CLTs that has emerged in recent years in connection with different branches of modern stochastic analysis. These limit theorems typically involve:
(a) an underlying infinite-dimensional Gaussian field $\mathbf{G}$ (like for instance a Wiener process), (b) a sequence of rescaled centered random vectors $F_{n}=F_{n}(\mathbf{G}), n \geqslant 1$, having the form of some highly non-linear functional of the field $\mathbf{G}$. For example, each $F_{n}$ may be defined as some collection of polynomial transformations of $\mathbf{G}$, possibly depending on a parameter that is integrated with respect to a deterministic measure (but much more general forms are possible). Objects of this type naturally appear e.g. in the high-frequency analysis of random fields on homogeneous spaces [31], fractional processes [32,43], Gaussian polymers [53], or random matrices [13,35].

In view of their intricate structure, it is in general not possible to meaningfully represent the vectors $F_{n}$ in terms of some linear transformation of independent (or weakly dependent) vectors, so that the usual analytical techniques based on stochastic independence and convolution (or mixing) cannot be applied. To overcome these difficulties, a recently developed line of research (see [36] for an introduction) has revealed that, by using tools from infinite-dimensional Gaussian analysis (e.g. the so-called Malliavin calculus of variations - see [42]) and under some regularity assumptions on $F_{n}$, one can control the distance between the distribution of $F_{n}$ and that of some Gaussian target by means of quantities that are no more complex than the fourth moment of $F_{n}$. The regularity assumptions on $F_{n}$ are usually expressed in terms of the projections of each $F_{n}$ on the eigenspaces of the Ornstein-Uhlenbeck semigroup associated with $\mathbf{G}[36,42]$.

In this area, the most prominent contribution is arguably the following one-dimensional inequality established by the first two authors (see, e.g., [36, Theorem 5.2.6]): let $f$ be the density of a random variable $F$, assume that $\int_{\mathbb{R}} x^{2} f(x) d x=1$, and that $F$ belongs to the $q$ th eigenspace of the Ornstein-Uhlenbeck semigroup of $\mathbf{G}$ (customarily called the $q$ th Wiener chaos of $\mathbf{G}$ ), then

$$
\begin{equation*}
\frac{1}{4} \int_{\mathbb{R}}\left|f(x)-\phi_{1}(x)\right| d x \leqslant \sqrt{\frac{1}{3}-\frac{1}{3 q}} \times \sqrt{\int_{\mathbb{R}} x^{4}\left(f(x)-\phi_{1}(x)\right) d x} \tag{1.1}
\end{equation*}
$$

where $\phi_{1}(x)=(2 \pi)^{-1 / 2} \exp \left(-x^{2} / 2\right)$ is the standard Gaussian density (one can prove that $\int_{\mathbb{R}} x^{4}\left(f(x)-\phi_{1}(x)\right) d x>0$ for $f$ as above). Note that $\int_{\mathbb{R}} x^{4} \phi_{1}(x) d x=3$. A standard use of hypercontractivity therefore allows one to deduce the so-called fourth moment theorem established in [44]: for a rescaled sequence $\left\{F_{n}\right\}$ of random variables living inside the qth Wiener chaos of $\mathbf{G}$, one has that $F_{n}$ converges in distribution to a standard Gaussian random variable if and only if the fourth moment of $F_{n}$ converges to 3 (and in this case the convergence is in the sense of total variation). See also [43].

The quantity $\int_{\mathbb{R}} x^{4}\left(f(x)-\phi_{1}(x)\right) d x$ appearing in (1.1) is often called the kurtosis of the density $f$ : it provides a rough measure of the discrepancy between the 'fatness' of the tails of $f$ and $\phi_{1}$. The systematic emergence of the normal distribution from the reduction of kurtosis, in such a general collection of probabilistic models, is a new phenomenon that we barely begin to understand. A detailed discussion of these results can be found in [36, Chapters 5 and 6]. M. Ledoux [27] has recently proved a striking extension of the fourth moment theorem to random variables living in the eigenspaces associated with a general Markov operator, whereas Refs. [17,24] contain similar statements in the framework of free probability. See also [34,37], respectively, for a connection with second order Poincaré inequalities, and for a general analytical characterization of cumulants on the Wiener space.

The estimate (1.1) is obtained by combining the Malliavin calculus of variations with the Stein's method for normal approximations [15,36]. Stein's method can be roughly described as a collection of analytical techniques, allowing one to measure the distance between random elements by controlling the regularity of the solutions to some specific ordinary (in dimension 1)
or partial (in higher dimensions) differential equations. The needed estimates are often expressed in terms of the same Stein factors that lie at the core of the present paper (see Section 2.3 for definitions). It is important to notice that the strength of these techniques significantly breaks down when dealing with normal approximations in dimension strictly greater than 1.

For instance, in view of the structure of the associated PDEs, for the time being there is no way to directly use Stein's method in order to deduce bounds in the multidimensional total variation distance. (This fact is demonstrated e.g. in Refs. [14,47], where multidimensional bounds are obtained for distances involving smooth test functions, as well as in [19], containing a quantitative version of the classical multidimensional CLT, with bounds on distances involving test functions that are indicators of convex sets: all these papers use some variations of the multidimensional Stein's method, but none of them achieves bounds in the total variation distance.)

In contrast, the results of this paper allow one to deduce a number of information-theoretical generalizations of (1.1) that are valid in any dimension. It is somehow remarkable that our techniques make a pervasive use of Stein factors, without ever applying Stein's method. As an illustration, we present here a multidimensional entropic fourth moment bound that will be proved in full generality in Section 4. For $d \geqslant 1$, we write $\phi_{d}(\mathbf{x})=\phi_{d}\left(x_{1}, \ldots, x_{d}\right)$ to indicate the Gaussian density $(2 \pi)^{-d / 2} \exp \left(-\left(x_{1}^{2}+\cdots+x_{d}^{2}\right) / 2\right),\left(x_{1}, \ldots, x_{d}\right) \in \mathbb{R}^{d}$. From now on, every random object is assumed to be defined on a common probability space $(\Omega, \mathcal{F}, P)$, with $E$ denoting expectation with respect to $P$.

Theorem 1.1 (Entropic fourth moment bound). Let $F_{n}=\left(F_{1, n}, \ldots, F_{d, n}\right)$ be a sequence of $d$-dimensional random vectors such that: (i) $F_{i, n}$ belongs to the $q_{i}$ th Wiener chaos of $\mathbf{G}$, with $1 \leqslant q_{1} \leqslant q_{2} \leqslant \cdots \leqslant q_{d}$; (ii) each $F_{i, n}$ has variance 1 ; (iii) $E\left[F_{i, n} F_{j, n}\right]=0$ for $i \neq j$, and (iv) the law of $F_{n}$ admits a density $f_{n}$ on $\mathbb{R}^{d}$. Write

$$
\Delta_{n}:=\int_{\mathbb{R}^{d}}\|\mathbf{x}\|^{4}\left(f_{n}(\mathbf{x})-\phi_{d}(\mathbf{x})\right) d \mathbf{x}
$$

where $\|\cdot\|$ stands for the Euclidean norm, and assume that $\Delta_{n} \rightarrow 0$, as $n \rightarrow \infty$. Then,

$$
\begin{equation*}
\int_{\mathbb{R}^{d}} f_{n}(\mathbf{x}) \log \frac{f_{n}(\mathbf{x})}{\phi_{d}(\mathbf{x})} d \mathbf{x}=O(1) \Delta_{n}\left|\log \Delta_{n}\right|, \tag{1.2}
\end{equation*}
$$

where $O(1)$ stands for a bounded numerical sequence, depending on $d, q_{1}, \ldots, q_{d}$ and on the sequence $\left\{F_{n}\right\}$.

As in the one-dimensional case, one has always that $\Delta_{n}>0$ for $f_{n}$ as in the previous statement. The quantity of the left-hand side of (1.2) equals of course the relative entropy of $f_{n}$. In view of the Csiszar-Kullback-Pinsker inequality (see [16,25,46]), according to which

$$
\begin{equation*}
\int_{\mathbb{R}^{d}} f_{n}(\mathbf{x}) \log \frac{f_{n}(\mathbf{x})}{\phi_{d}(\mathbf{x})} d \mathbf{x} \geqslant \frac{1}{2}\left(\int_{\mathbb{R}^{d}}\left|f_{n}(\mathbf{x})-\phi_{d}(\mathbf{x})\right| d \mathbf{x}\right)^{2} \tag{1.3}
\end{equation*}
$$

relation (1.2) then translates in a bound on the square of the total variation distance between $f_{n}$ and $\phi_{d}$, where the dependence in $\Delta_{n}$ hinges on the order of the chaoses only via a multiplicative constant. This bound agrees up to a logarithmic factor with the estimates in smoother
distances established in [41] (see also [39]), where it is proved that there exists a constant $K_{0}=K_{0}\left(d, q_{1}, \ldots, q_{d}\right)$ such that

$$
\mathbf{W}_{1}\left(f_{n}, \phi_{d}\right) \leqslant K_{0} \Delta_{n}^{1 / 2}
$$

where $\mathbf{W}_{1}$ stands for the usual Wasserstein distance of order 1. Relation (1.2) also drastically improves the bounds that can be deduced from [33], yielding that, as $n \rightarrow \infty$,

$$
\int_{\mathbb{R}^{d}}\left|f_{n}(\mathbf{x})-\phi_{d}(\mathbf{x})\right| d \mathbf{x}=O(1) \Delta_{n}^{\alpha_{d}}
$$

where $\alpha_{d}$ is any strictly positive number verifying $\alpha_{d}<\frac{1}{1+(d+1)\left(3+4 d\left(q_{d}-1\right)\right)}$, and the symbol $O$ (1) stands again for some bounded numerical sequence. The estimate (1.2) seems to be largely outside the scope of any other available technique. Our results will also show that convergence in relative entropy is a necessary and sufficient condition for CLTs involving random vectors whose components live in a fixed Wiener chaos. As in [33,40], an important tool for establishing our main results is the Carbery-Wright inequality [11], providing estimates on the small ball probabilities associated with polynomial transformations of Gaussian vectors. Observe also that, via the Talagrand's transport inequality [52], our bounds trivially provide estimates on the 2-Wasserstein distance $\mathbf{W}_{2}\left(f_{n}, \phi_{d}\right)$ between $f_{n}$ and $\phi_{d}$, for every $d \geqslant 1$. Notice once again that, in Theorem 1.1 and its generalizations, no additional regularity (a part from the fact of being elements of a fixed Wiener chaos) is required from the components of the vector $F_{n}$. One should contrast this situation with the recent work by $\mathrm{Hu}, \mathrm{Lu}$ and Nualart [20], where the authors achieve fourth moment bounds on the supremum norm of the difference $f_{n}-\phi_{d}$, under very strong additional conditions expressed in terms of the finiteness of negative moments of Malliavin matrices.

We stress that, although our principal motivation comes from asymptotic problems on a Gaussian space, the methods developed in Section 2 are general. In fact, at the heart of the present work lie the powerful equivalences (2.45)-(2.46) (which can be considered as a new form of so-called Stein identities) that are valid under very weak assumptions on the target density; it is also easy to uncover a wide variety of extensions and generalizations so that we expect that our tools can be adapted to deal with a much wider class of multidimensional distributions.

The connection between Stein identities and information theory has already been noted in the literature (although only in dimension 1). For instance, explicit applications are known in the context of Poisson and compound Poisson approximations [7,49], and recently several promising identities have been discovered for some discrete $[28,48]$ as well as continuous distributions [26,29,45]. However, with the exception of [29], the existing literature seems to be silent about any connection between entropic CLTs and Stein's identities for normal approximations. To the best of our knowledge, together with [29] (which however focuses on bounds of a completely different nature) the present paper contains the first relevant study of the relations between the two topics.

Remark on notation. Given random vectors $X, Y$ with values in $\mathbb{R}^{d}(d \geqslant 1)$ and densities $f_{X}$, $f_{Y}$, respectively, we shall denote by $\mathbf{T V}\left(f_{X}, f_{Y}\right)$ the total variation distance between $f_{X}$ and $f_{Y}$ (and thus between the laws of $X$ and $Y$ ). Recall that we have the representations

$$
\begin{align*}
\mathbf{T V}\left(f_{X}, f_{Y}\right) & =\sup _{A \in \mathscr{B}\left(\mathbb{R}^{d}\right)}|P[X \in A]-P[Y \in A]| \\
& =\frac{1}{2} \sup _{\|h\|_{\infty} \leqslant 1}|E[h(X)]-E[h(Y)]| \\
& =\frac{1}{2} \int_{\mathbb{R}^{d}}\left|f_{X}(\mathbf{x})-f_{Y}(\mathbf{x})\right| d \mathbf{x}=: \frac{1}{2}\left\|f_{X}-f_{Y}\right\|_{1}, \tag{1.4}
\end{align*}
$$

where (here and throughout the paper) $d \mathbf{x}$ is shorthand for the Lebesgue measure on $\mathbb{R}^{d}$. In order to simplify the discussion, we shall sometimes use the shorthand notation

$$
\mathbf{T V}(X, Y)=\mathbf{T V}\left(f_{X}, f_{Y}\right)
$$

It is a well-known fact that the topology induced by TV, over the class of probability measures on $\mathbb{R}^{d}$, is strictly stronger than the topology of convergence in distribution (see e.g. [18, Chapter 11] or [36, Appendix C]). Finally, we agree that every logarithm in the paper has base $e$.

To enhance the readability of the text, the next Section 1.2 contains an intuitive description of our method in dimension one.

### 1.2. Illustration of the method in dimension one

Let $F$ be a random variable with density $f: \mathbb{R} \rightarrow[0, \infty)$, and let $Z$ be a standard Gaussian random variable with density $\phi_{1}$. We shall assume that $E[F]=0$ and $E\left[F^{2}\right]=1$, and that $Z$ and $F$ are stochastically independent. As anticipated, we are interested in bounding the relative entropy of $F$ (with respect to $Z$ ), which is given by the quantity

$$
D(F \| Z)=\int_{\mathbb{R}} f(x) \log \left(f(x) / \phi_{1}(x)\right) d x
$$

Recall also that, in view of the Pinsker-Csiszar-Kullback inequality, one has that

$$
\begin{equation*}
2 \mathbf{T V}\left(f, \phi_{1}\right) \leqslant \sqrt{2 D(F \| Z)} \tag{1.5}
\end{equation*}
$$

Our aim is to deduce a bound on $D(F \| Z)$ that is expressed in terms of the so-called Stein factor associated with $F$. Whenever it exists, such a factor is a mapping $\tau_{F}: \mathbb{R} \rightarrow \mathbb{R}$ that is uniquely determined (up to negligible sets) by requiring that $\tau_{F}(F) \in L^{1}$ and

$$
E[F g(F)]=E\left[\tau_{F}(F) g^{\prime}(F)\right]
$$

for every smooth test function $g$. Specifying $g(x)=x$ implies, in particular, that $E\left[\tau_{F}(F)\right]=$ $E\left[F^{2}\right]=1$. It is easily seen that, under standard regularity assumptions, a version of $\tau_{F}$ is given by $\tau_{F}(x)=(f(x))^{-1} \int_{x}^{\infty} z f(z) d z$, for $x$ in the support of $f$ (in particular, the Stein factor of $Z$ is 1). The relevance of the factor $\tau_{F}$ in comparing $F$ with $Z$ is actually revealed by the following Stein's bound $[15,36]$, which is one of the staples of Stein's method:

$$
\begin{equation*}
\mathbf{T V}\left(f, \phi_{1}\right)=\sup \left|E\left[g^{\prime}(F)\right]-E[F g(F)]\right| \tag{1.6}
\end{equation*}
$$

where the supremum runs over all continuously differentiable functions $g: \mathbb{R} \rightarrow \mathbb{R}$ satisfying $\|g\|_{\infty} \leqslant \sqrt{2 / \pi}$ and $\left\|g^{\prime}\right\|_{\infty} \leqslant 2$. In particular, from (1.6) one recovers the bound in total variation

$$
\begin{equation*}
\mathbf{T V}\left(f, \phi_{1}\right) \leqslant 2 E\left[\left|1-\tau_{F}(F)\right|\right], \tag{1.7}
\end{equation*}
$$

providing a formal meaning to the intuitive fact that the distributions of $F$ and $Z$ are close whenever $\tau_{F}$ is close to $\tau_{Z}$, that is, whenever $\tau_{F}$ is close to 1 . To motivate the reader, we shall now present a simple illustration of how the estimate (1.7) applies to the usual CLT.

Example 1.2. Let $\left\{F_{i}: i \geqslant 1\right\}$ be a sequence of i.i.d. copies of $F$, set $S_{n}=n^{-1 / 2} \sum_{i=1}^{n} F_{i}$ and assume that $E\left[\tau_{F}(F)^{2}\right]<+\infty$ (a simple sufficient condition for this to hold is e.g. that $f$ has compact support, and $f$ is bounded from below inside its support). Then, using e.g. [51, Lemma 2],

$$
\begin{equation*}
\tau_{S_{n}}\left(S_{n}\right)=\frac{1}{n} E\left[\sum_{i=1}^{n} \tau_{F}\left(F_{i}\right) \mid S_{n}\right] . \tag{1.8}
\end{equation*}
$$

Since (by definition) $E\left[\tau_{S_{n}}\left(S_{n}\right)\right]=E\left[\tau_{F}\left(F_{i}\right)\right]=1$ for all $i=1, \ldots, n$ we get

$$
\begin{align*}
E\left[\left(1-\tau_{S_{n}}\left(S_{n}\right)\right)^{2}\right] & =E\left[\left(\frac{1}{n} E\left[\sum_{i=1}^{n}\left(1-\tau_{F}\left(F_{i}\right)\right) \mid F\right]\right)^{2}\right] \\
& \leqslant \frac{1}{n^{2}} E\left[\left(\sum_{i=1}^{n}\left(1-\tau_{F}\left(F_{i}\right)\right)\right)^{2}\right] \\
& =\frac{1}{n^{2}} \operatorname{Var}\left(\sum_{i=1}^{n}\left(1-\tau_{F}\left(F_{i}\right)\right)\right)=\frac{E\left[\left(1-\tau_{F}(F)\right)^{2}\right]}{n} \tag{1.9}
\end{align*}
$$

In particular, writing $f_{n}$ for the density of $S_{n}$, we deduce from (1.7) that

$$
\begin{equation*}
\mathbf{T V}\left(f_{n}, \phi_{1}\right) \leqslant 2 \frac{\operatorname{Var}\left(\tau_{F}(F)\right)^{1 / 2}}{\sqrt{n}} \tag{1.10}
\end{equation*}
$$

We shall demonstrate in Section 3 and Section 4 that the quantity $E\left[\left|1-\tau_{F}(F)\right|\right]$ (as well as its multidimensional generalizations) can be explicitly controlled whenever $F$ is a smooth functional of a Gaussian field. In view of these observations, the following question is therefore natural: can one bound $D(F \| Z)$ by an expression analogous to the right-hand side of (1.7)?

Our strategy for connecting $\tau_{F}(F)$ and $D(F \| Z)$ is based on an integral version of the classical de Bruijn's formula of information theory. To introduce this result, for $t \in[0,1]$ denote by $f_{t}$ the density of $F_{t}=\sqrt{t} F+\sqrt{1-t} Z$, in such a way that $f_{1}=f$ and $f_{0}=\phi_{1}$. Of course $f_{t}(x)=$ $E\left[\phi_{1}((x-\sqrt{t} F) / \sqrt{1-t})\right] / \sqrt{1-t}$ has support $\mathbb{R}$ and is $C^{\infty}$ for all $t<1$. We shall denote by $\rho_{t}=\left(\log f_{t}\right)^{\prime}$ the score function of $F_{t}$ (which is, by virtue of the preceding remark, well-defined at all $t<1$ irrespective of the properties of $F$ ). For every $t<1$, the mapping $\rho_{t}$ is completely characterized by the fact that

$$
\begin{equation*}
E\left[g^{\prime}\left(F_{t}\right)\right]=-E\left[g\left(F_{t}\right) \rho_{t}\left(F_{t}\right)\right] \tag{1.11}
\end{equation*}
$$

for every smooth test function $g$. We also write, for $t \in[0,1)$,

$$
J\left(F_{t}\right)=E\left[\rho_{t}\left(F_{t}\right)^{2}\right]=\int_{\mathbb{R}} \frac{f_{t}^{\prime}(x)^{2}}{f_{t}(x)} d x
$$

for the Fisher information of $F_{t}$, and we observe that

$$
0 \leqslant E\left[\left(F_{t}+\rho_{t}\left(F_{t}\right)\right)^{2}\right]=J\left(F_{t}\right)-1=: J_{s t}\left(F_{t}\right)
$$

where $J_{s t}\left(F_{t}\right)$ is the so-called standardized Fisher information of $F_{t}$ (note that $J_{s t}\left(F_{0}\right)=$ $J_{s t}(Z)=0$ ). With this notation in mind, de Bruijn's formula (in an integral and rescaled version due to Barron [8]) reads

$$
\begin{equation*}
D(F \| Z)=\int_{0}^{1} \frac{J\left(F_{t}\right)-1}{2 t} d t=\int_{0}^{1} \frac{J_{s t}\left(F_{t}\right)}{2 t} d t \tag{1.12}
\end{equation*}
$$

(see Lemma 2.3 below for a multidimensional statement).
Remark 1.3. Using the standard relation $J_{s t}\left(F_{t}\right) \leqslant t J_{s t}(F)+(1-t) J_{s t}(Z)=t J_{s t}(F)$ (see e.g. [21, Lemma 1.21]), we deduce the upper bound

$$
\begin{equation*}
D(F \| Z) \leqslant \frac{1}{2} J_{s t}(F) \tag{1.13}
\end{equation*}
$$

a result which is often proved by using entropy power inequalities (see also Shimizu [50]). Formula (1.13) is a quantitative counterpart to the intuitive fact that the distributions of $F$ and $Z$ are close, whenever $J_{s t}(F)$ is close to zero. Using (1.5) we further deduce that closeness between the Fisher informations of $F$ and $Z$ (i.e. $J_{s t}(F) \approx 0$ ) or between the entropies of $F$ and $Z$ (i.e. $D(F \| Z) \approx 0$ ) both imply closeness in terms of the total variation distance, and hence in terms of many more probability metrics. This observation lies at the heart of the approach from [8,10,22] where a fine analysis of the behavior of $\rho_{F}(F)$ over convolutions (through projection inequalities in the spirit of (1.8)) is used to provide explicit bounds on the Fisher information distance which in turn are transformed, by means of de Bruijn's identity (1.12), into bounds on the relative entropy. We will see in Section 4 that the bound (1.13) is too crude to be of use in the applications we are interested in.

Our key result in dimension 1 is the following statement (see Theorem 2.10 for a general multidimensional version), providing a new representation of relative entropy in terms of Stein factors. From now on, we denote by $C_{c}^{1}$ the class of all functions $g: \mathbb{R} \rightarrow \mathbb{R}$ that are continuously differentiable and with compact support.

Proposition 1.4. Let the previous notation prevail. We have

$$
\begin{equation*}
D(F \| Z)=\frac{1}{2} \int_{0}^{1} \frac{t}{1-t} E\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]^{2}\right] d t \tag{1.14}
\end{equation*}
$$

Proof. Using $\rho_{Z}(Z)=-Z$ we see that, for any function $g \in C_{c}^{1}$, one has

$$
\begin{aligned}
E & {\left[Z\left(1-\tau_{F}(F)\right) g(\sqrt{t} F+\sqrt{1-t} Z)\right] } \\
& =\sqrt{1-t} E\left[\left(1-\tau_{F}(F)\right) g^{\prime}(\sqrt{t} F+\sqrt{1-t} Z)\right] \\
& =\sqrt{1-t}\left\{E\left[g^{\prime}\left(F_{t}\right)\right]-\frac{1}{\sqrt{t}} E\left[F g\left(F_{t}\right)\right]\right\} \\
& =\frac{\sqrt{1-t}}{t}\left\{E\left[g^{\prime}\left(F_{t}\right)\right]-E\left[F_{t} g\left(F_{t}\right)\right]\right\}=-\frac{\sqrt{1-t}}{t} E\left[\left(\rho_{t}\left(F_{t}\right)+F_{t}\right) g\left(F_{t}\right)\right],
\end{aligned}
$$

yielding the representation

$$
\begin{equation*}
\rho_{t}\left(F_{t}\right)+F_{t}=-\frac{t}{\sqrt{1-t}} E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right] . \tag{1.15}
\end{equation*}
$$

This implies

$$
J\left(F_{t}\right)-1=E\left[\left(\rho_{t}\left(F_{t}\right)+F_{t}\right)^{2}\right]=\frac{t^{2}}{1-t} E\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]^{2}\right],
$$

and the desired conclusion follows from de Bruijn's identity (1.12).

To properly control the integral on the right-hand side of (1.14), we need to deal with the fact that the mapping $t \mapsto \frac{t}{1-t}$ is not integrable in $t=1$, so that we cannot directly apply the estimate $E\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]^{2}\right] \leqslant \operatorname{Var}\left(\tau_{F}(F)\right)$ to deduce the desired bound. Intuitively, one has to exploit the fact that the mapping $t \mapsto E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]$ satisfies $E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{1}\right]=0$, thus in principle compensating for the singularity at $t \approx 1$.

As we will see below, one can make this heuristic precise provided there exist three constants $c, \delta, \eta>0$ such that

$$
\begin{align*}
E\left[\left|\tau_{F}(F)\right|^{2+\eta}\right] & <\infty \quad \text { and } \\
E\left[\left|E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]\right|\right] & \leqslant c t^{-1}(1-t)^{\delta}, \quad 0<t \leqslant 1 . \tag{1.16}
\end{align*}
$$

Under the assumptions appearing in condition (1.16), the following strategy can indeed be implemented in order to deduce a satisfactory bound. First split the integral in two parts: for every $0<\varepsilon \leqslant 1$,

$$
\begin{align*}
2 D(F \| Z) & \leqslant E\left[\left(1-\tau_{F}(F)\right)^{2}\right] \int_{0}^{1-\varepsilon} \frac{t d t}{1-t}+\int_{1-\varepsilon}^{1} \frac{t}{1-t} E\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]^{2}\right] d t \\
& \leqslant E\left[\left(1-\tau_{F}(F)\right)^{2}\right]|\log \varepsilon|+\int_{1-\varepsilon}^{1} \frac{t}{1-t} E\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]^{2}\right] d t \tag{1.17}
\end{align*}
$$

the last inequality being a consequence of $\int_{0}^{1-\varepsilon} \frac{t d t}{1-t}=\int_{\varepsilon}^{1} \frac{(1-u) d u}{u} \leqslant \int_{\varepsilon}^{1} \frac{d u}{u}=-\log \varepsilon$. To deal with the second term in (1.17), let us observe that, by using in particular the Hölder inequality and the convexity of the function $x \mapsto|x|^{\eta+2}$, one deduces from (1.16) that

$$
\begin{align*}
E & {\left[E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]{ }^{2}\right] } \\
& =E\left[\left|E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]\right|^{\frac{\eta}{\eta+1}}\left|E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]\right|^{\frac{\eta+2}{\eta+1}}\right] \\
& \leqslant E\left[\left|E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]\right|\right]^{\frac{\eta}{\eta+1}} \times E\left[\left|E\left[Z\left(1-\tau_{F}(F)\right) \mid F_{t}\right]\right|^{\eta+2}\right]^{\frac{1}{\eta+1}} \\
& \leqslant c^{\frac{\eta}{\eta+1}} t^{-\frac{\eta}{\eta+1}}(1-t)^{\frac{\delta \eta}{\eta+1}} \times E\left[|Z|^{\eta+2}\right]^{\frac{1}{n+1}} \times E\left[\left|1-\tau_{F}(F)\right|^{\eta+2}\right]^{\frac{1}{\eta+1}} \\
& \leqslant c^{\frac{\eta}{\eta+1}} t^{-1}(1-t)^{\frac{\delta \eta}{\eta+1}} \times 2 E\left[|Z|^{\eta+2}\right]^{\frac{1}{n+1}}\left(1+E\left[\left|\tau_{F}(F)\right|^{\eta+2}\right]\right)^{\frac{1}{\eta+1}} \\
& =C_{\eta} t^{-1}(1-t)^{\frac{\delta \eta}{\eta+1}}, \tag{1.18}
\end{align*}
$$

with

$$
C_{\eta}:=2 c^{\frac{\eta}{\eta+1}} E\left[|Z|^{\eta+2}\right]^{\frac{1}{\eta+1}}\left(1+E\left[\left|\tau_{F}(F)\right|^{\eta+2}\right]\right)^{\frac{1}{\eta+1}} .
$$

By virtue of (1.17) and (1.18), the term $D(F \| Z)$ is eventually amenable to analysis, and one obtains:

$$
\begin{aligned}
2 D(F \| Z) & \leqslant E\left[\left(1-\tau_{F}(F)\right)^{2}\right]|\log \varepsilon|+C_{\eta} \int_{1-\varepsilon}^{1}(1-t)^{\frac{\delta \eta}{\eta+1}-1} d t \\
& =E\left[\left(1-\tau_{F}(F)\right)^{2}\right]|\log \varepsilon|+\frac{C_{\eta}(\eta+1)}{\delta \eta} \varepsilon^{\frac{\delta \eta}{\eta+1}}
\end{aligned}
$$

Assuming finally that $E\left[\left(1-\tau_{F}(F)\right)^{2}\right] \leqslant 1$ (recall that, in the applications we are interested in, such a quantity is meant to be close to 0 ) we can optimize over $\varepsilon$ and choose $\varepsilon=E[(1-$ $\left.\left.\tau_{F}(F)\right)^{2}\right]^{\frac{\eta+1}{\delta \eta}}$, which leads to

$$
\begin{align*}
D(F \| Z) \leqslant & \frac{\eta+1}{2 \delta \eta} E\left[\left(1-\tau_{F}(F)\right)^{2}\right]\left|\log E\left[\left(1-\tau_{F}(F)\right)^{2}\right]\right| \\
& +\frac{C_{\eta}(\eta+1)}{2 \delta \eta} E\left[\left(1-\tau_{F}(F)\right)^{2}\right] \tag{1.19}
\end{align*}
$$

Clearly, combining (1.19) with (1.5), one also obtains an estimate in total variation which agrees with (1.7) up to the square root of a logarithmic factor.

The problem is now how to identify sufficient conditions on the law of $F$ for (1.16) to hold; we shall address this issue by means of two auxiliary results. We start with a useful technical lemma, that has been suggested to us by Guillaume Poly.

Lemma 1.5. Let $X$ be an integrable random variable and let $Y$ be an $\mathbb{R}^{d}$-valued random vector having an absolutely continuous distribution. Then

$$
\begin{equation*}
E|E[X \mid Y]|=\sup E[X g(Y)] \tag{1.20}
\end{equation*}
$$

where the supremum is taken over all $g \in C_{c}^{1}$ such that $\|g\|_{\infty} \leqslant 1$.
Proof. Since $|\operatorname{sign}(E[X \mid Y])|=1$ we have, by using e.g. Lusin's Theorem,

$$
E|E[X \mid Y]|=E[X \operatorname{sign}(E[X \mid Y])] \leqslant \sup E(X g(Y))
$$

To see the reversed inequality, observe that, for any $g$ bounded by 1 ,

$$
|E(X g(Y))|=|E(E(X \mid Y) g(Y))| \leqslant E|E[X \mid Y]|
$$

The lemma is proved.
Our next statement relates (1.16) to the problem of estimating the total variation distance between $F$ and $\sqrt{t} F+\sqrt{1-t} x$ for any $x \in \mathbb{R}$ and $0<t \leqslant 1$.

Lemma 1.6. Assume that, for some $\kappa, \alpha>0$,

$$
\begin{equation*}
\mathbf{T V}(\sqrt{t} F+\sqrt{1-t} x, F) \leqslant \kappa(1+|x|) t^{-1}(1-t)^{\alpha}, \quad x \in \mathbb{R}, t \in(0,1] \tag{1.21}
\end{equation*}
$$

Then (1.16) holds, with $\delta=\frac{1}{2} \wedge \alpha$ and $c=4(\kappa+1)$.
Proof. Take $g \in C_{c}^{1}$ such that $\|g\|_{\infty} \leqslant 1$. Then, by independence of $Z$ and $F$,

$$
\begin{aligned}
E\left[Z\left(1-\tau_{F}(F)\right) g\left(F_{t}\right)\right] & =E\left[g\left(F_{t}\right) Z\right]-E\left[Z g\left(F_{t}\right) \tau_{F}(F)\right] \\
& =E\left[g\left(F_{t}\right) Z\right]-\sqrt{1-t} E\left[\tau_{F}(F) g^{\prime}\left(F_{t}\right)\right] \\
& =E\left[Z\left(g\left(F_{t}\right)-g(F)\right)\right]-\sqrt{\frac{1-t}{t}} E\left[g\left(F_{t}\right) F\right]
\end{aligned}
$$

so that, since $\|g\|_{\infty} \leqslant 1$ and $E|F| \leqslant \sqrt{E\left[F^{2}\right]}=1$,

$$
\begin{aligned}
\left|E\left[Z\left(1-\tau_{F}(F)\right) g\left(F_{t}\right)\right]\right| & \leqslant\left|E\left[Z\left(g\left(F_{t}\right)-g(F)\right)\right]\right|+\sqrt{\frac{1-t}{t}} \\
& \leqslant\left|E\left[Z\left(g\left(F_{t}\right)-g(F)\right)\right]\right|+t^{-1} \sqrt{1-t}
\end{aligned}
$$

We have furthermore

$$
\begin{aligned}
\left|E\left[Z\left(g\left(F_{t}\right)-g(F)\right)\right]\right| & =\left|\int_{\mathbb{R}} x E[g(\sqrt{t} F+\sqrt{1-t} x)-g(F)] \phi_{1}(x) d x\right| \\
& \leqslant 2 \int_{\mathbb{R}}|x| \mathbf{T V}(\sqrt{t} F+\sqrt{1-t} x, F) \phi_{1}(x) d x \\
& \leqslant 2 \kappa t^{-1}(1-t)^{\alpha} \int_{\mathbb{R}}|x|(1+|x|) \phi_{1}(x) d x \\
& \leqslant 4 \kappa t^{-1}(1-t)^{\alpha}
\end{aligned}
$$

Inequality (1.16) now follows by applying Lemma 1.5.
As anticipated, in Section 4 (see Lemma 4.4 for a precise statement) we will describe a wide class of distributions satisfying (1.21). The previous discussion yields finally the following statement, answering the original question of providing a bound on $D(F \| Z)$ that is comparable with the estimate (1.7).

Theorem 1.7. Let $F$ be a random variable with density $f: \mathbb{R} \rightarrow[0, \infty)$, satisfying $E[F]=0$ and $E\left[F^{2}\right]=1$. Let $Z \sim \mathscr{N}(0,1)$ be a standard Gaussian variable (independent of $F$ ). If, for some $\alpha, \kappa, \eta>0$, one has

$$
\begin{equation*}
E\left[\left|\tau_{F}(F)\right|^{2+\eta}\right]<\infty \tag{1.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathbf{T V}(\sqrt{t} F+\sqrt{1-t} x, F) \leqslant \kappa(1+|x|) t^{-1}(1-t)^{\alpha}, \quad x \in \mathbb{R}, t \in(0,1] \tag{1.23}
\end{equation*}
$$

then, provided $\Delta:=E\left[\left(1-\tau_{F}(F)\right)^{2}\right] \leqslant 1$,

$$
\begin{equation*}
D(F \| Z) \leqslant \frac{\eta+1}{(1 \wedge 2 \alpha) \eta} \Delta|\log \Delta|+\frac{C_{\eta}(\eta+1)}{(1 \wedge 2 \alpha) \eta} \Delta \tag{1.24}
\end{equation*}
$$

where

$$
C_{\eta}=2(4 \kappa+4)^{\frac{\eta}{\eta+1}} E\left[|Z|^{\eta+2}\right]^{\frac{1}{\eta+1}}\left(1+E\left[\left|\tau_{F}(F)\right|^{\eta+2}\right]\right)^{\frac{1}{\eta+1}} .
$$

### 1.3. Plan

The rest of the paper is organized as follows. In Section 2 we will prove that Theorem 1.7 can be generalized to a fully multidimensional setting. Section 3 contains some general results related to (infinite-dimensional) Gaussian stochastic analysis. Finally, in Section 4 we shall apply our estimates in order to deduce general bounds of the type appearing in Theorem 1.1.

## 2. Entropy bounds via de Bruijn's identity and Stein matrices

In Section 2.1 and Section 2.2 we discuss some preliminary notions related to the theory of information (definitions, notations and main properties). Section 2.3 contains the proof of a new integral formula, allowing one to represent the relative entropy of a given random vector in terms of a Stein matrix. The reader is referred to the monograph [21], as well as to [1, Chapter 10], for any unexplained definition and result concerning information theory.

### 2.1. Entropy

Fix an integer $d \geqslant 1$. Throughout this section, we consider a $d$-dimensional square-integrable and centered random vector $F=\left(F_{1}, \ldots, F_{d}\right)$ with covariance matrix $B>0$. We shall assume that the law of $F$ admits a density $f=f_{F}$ (with respect to the Lebesgue measure) with support $S \subseteq \mathbb{R}^{d}$. No other assumptions on the distribution of $F$ will be needed. We recall that the differential entropy (or, simply, the entropy) of $F$ is given by the quantity $\operatorname{Ent}(F):=-E[\log f(F)]=$ $-\int_{\mathbb{R}^{d}} f(\mathbf{x}) \log f(\mathbf{x}) d \mathbf{x}=-\int_{S} f(\mathbf{x}) \log f(\mathbf{x}) d \mathbf{x}$, where we have adopted (here and for the rest of the paper) the standard convention $0 \log 0:=0$. Note that $\operatorname{Ent}(F)=\operatorname{Ent}(F+c)$ for all $c \in \mathbb{R}^{d}$, i.e. entropy is location invariant.

As discussed above, we are interested in estimating the distance between the law of $F$ and the law of a $d$-dimensional centered Gaussian vector $Z=\left(Z_{1}, \ldots, Z_{d}\right) \sim \mathscr{N}_{d}(0, C)$, where $C>0$ is the associated covariance matrix. Our measure of the discrepancy between the distributions of $F$ and $Z$ is the relative entropy (often called Kullback-Leibler divergence or information entropy)

$$
\begin{equation*}
D(F \| Z):=E[\log (f(F) / \phi(F))]=\int_{\mathbb{R}^{d}} f(\mathbf{x}) \log \left(\frac{f(\mathbf{x})}{\phi(\mathbf{x})}\right) d \mathbf{x} \tag{2.25}
\end{equation*}
$$

where $\phi=\phi_{d}(\cdot ; C)$ is the density of $Z$. It is easy to compute the Gaussian entropy $\operatorname{Ent}(Z)=$ $1 / 2 \log \left((2 \pi e)^{d}|C|\right)$ (where $|C|$ is the determinant of $C$ ), from which we deduce the following alternative expression for the relative entropy

$$
\begin{equation*}
0 \leqslant D(F \| Z)=\operatorname{Ent}(Z)-\operatorname{Ent}(F)+\frac{\operatorname{tr}\left(C^{-1} B\right)-d}{2} \tag{2.26}
\end{equation*}
$$

where 'tr' stands for the usual trace operator. If $Z$ and $F$ have the same covariance matrix then the relative entropy is simply the entropy gap between $F$ and $Z$ so that, in particular, one infers from (2.26) that $Z$ has maximal entropy among all absolutely continuous random vectors with covariance matrix $C$.

We stress that the relative entropy $D$ does not define a bona fide probability distance (for absence of a triangle inequality, as well as for lack of symmetry): however, one can easily translate
estimates on the relative entropy in terms of the total variation distance, using the already recalled Pinsker-Csiszar-Kullback inequality (1.3). In the next subsection, we show how one can represent the quantity $D(F \| Z)$ as the integral of the standardized Fisher information of some adequate interpolation between $F$ and $Z$.

### 2.2. Fisher information and de Bruijn's identity

Without loss of generality, we may assume for the rest of the paper that the vectors $F$ and $Z$ (as defined in the previous Section 2.1) are stochastically independent. For every $t \in[0,1]$, we define the centered random vector $F_{t}:=\sqrt{t} F+\sqrt{1-t} Z$, in such a way that $F_{0}=Z$ and $F_{1}=F$. It is clear that $F_{t}$ is centered and has covariance $\Gamma_{t}=t B+(1-t) C>0$; moreover, whenever $t \in[0,1), F_{t}$ has a strictly positive and infinitely differentiable density, that we shall denote by $f_{t}$ (see e.g. [23, Lemma 3.1] for more details). For every $t \in[0,1)$, we define the score of $F_{t}$ as the $\mathbb{R}^{d}$-valued function given by

$$
\begin{equation*}
\rho_{t}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}: \quad \mathbf{x} \mapsto \rho_{t}(\mathbf{x})=\left(\rho_{t, 1}(\mathbf{x}), \ldots, \rho_{t, d}(\mathbf{x})\right)^{T}:=\nabla \log f_{t}(\mathbf{x}), \tag{2.27}
\end{equation*}
$$

with $\nabla$ the usual gradient in $\mathbb{R}^{d}$ (note that we will systematically regard the elements of $\mathbb{R}^{d}$ as column vectors). The quantity $\rho_{t}(\mathbf{x})$ is of course well-defined for every $\mathbf{x} \in \mathbb{R}^{d}$ and every $t \in[0,1)$; moreover, it is easily seen that the random vector $\rho_{t}\left(F_{t}\right)$ is completely characterized (up to sets of $P$-measure zero) by the relation

$$
\begin{equation*}
E\left[\rho_{t}\left(F_{t}\right) g\left(F_{t}\right)\right]=-E\left[\nabla g\left(F_{t}\right)\right] \tag{2.28}
\end{equation*}
$$

holding for every smooth function $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$. Selecting $g=1$ in (2.28), one sees that $\rho_{t}\left(F_{t}\right)$ is a centered random vector. The covariance matrix of $\rho_{t}\left(F_{t}\right)$ is denoted by

$$
\begin{equation*}
J\left(F_{t}\right):=E\left[\rho_{t}\left(F_{t}\right) \rho_{t}\left(F_{t}\right)^{T}\right] \tag{2.29}
\end{equation*}
$$

(with components $J\left(F_{t}\right)_{i j}=E\left[\rho_{t, i}\left(F_{t}\right) \rho_{t, j}\left(F_{t}\right)\right]$ for $1 \leqslant i, j \leqslant d$ ), and is customarily called the Fisher information matrix of $F_{t}$. Focusing on the case $t=0$, one sees immediately that the Gaussian vector $F_{0}=Z \sim \mathscr{N}_{d}(0, C)$ has linear score function $\rho_{0}(\mathbf{x})=\rho_{Z}(\mathbf{x})=-C^{-1} \mathbf{x}$ and Fisher information $J\left(F_{0}\right)=J(Z)=C^{-1}$.

Remark 2.1. Fix $t \in[0,1)$. Using formula (2.28) one deduces that a version of $\rho_{t}\left(F_{t}\right)$ is given by the conditional expectation $-(1-t)^{-1 / 2} E\left[C^{-1} Z \mid F_{t}\right]$, from which we infer that the matrix $J\left(F_{t}\right)$ is well-defined and its entries are all finite.

For $t \in[0,1)$, we define the standardized Fisher information matrix of $F_{t}$ as

$$
\begin{equation*}
J_{s t}\left(F_{t}\right):=\Gamma_{t} E\left[\left(\rho_{t}\left(F_{t}\right)+\Gamma_{t}^{-1} F_{t}\right)\left(\rho_{t}\left(F_{t}\right)+\Gamma_{t}^{-1} F_{t}\right)^{T}\right]=\Gamma_{t} J\left(F_{t}\right)-I_{d} \tag{2.30}
\end{equation*}
$$

where $I_{d}$ is the $d \times d$ identity matrix, and the last equality holds because $E\left[\rho_{t}\left(F_{t}\right) F_{t}\right]=-I_{d}$. Note that the positive semidefinite matrix $\Gamma_{t}^{-1} J_{s t}\left(F_{t}\right)=J\left(F_{t}\right)-\Gamma_{t}^{-1}$ is the difference between
the Fisher information matrix of $F_{t}$ and that of a Gaussian vector having distribution $\mathscr{N}_{d}\left(0, \Gamma_{t}\right)$. Observe that

$$
\begin{equation*}
J_{s t}\left(F_{t}\right):=E\left[\left(\rho_{t}^{\star}\left(F_{t}\right)+F_{t}\right)\left(\rho_{t}^{\star}\left(F_{t}\right)+F_{t}\right)^{T}\right] \Gamma_{t}^{-1} \tag{2.31}
\end{equation*}
$$

where the vector

$$
\begin{equation*}
\rho_{t}^{\star}\left(F_{t}\right)=\left(\rho_{t, 1}^{\star}\left(F_{t}\right), \ldots, \rho_{t, d}^{\star}\left(F_{t}\right)\right)^{T}:=\Gamma_{t} \rho_{t}\left(F_{t}\right) \tag{2.32}
\end{equation*}
$$

is completely characterized (up to sets of $P$-measure 0 ) by the equation

$$
\begin{equation*}
E\left[\rho_{t}^{\star}\left(F_{t}\right) g\left(F_{t}\right)\right]=-\Gamma_{t} E\left[\nabla g\left(F_{t}\right)\right], \tag{2.33}
\end{equation*}
$$

holding for every smooth test function $g$.

Remark 2.2. Of course the above information theoretic quantities are not defined only for Gaussian mixtures of the form $F_{t}$ but more generally for any random vector satisfying the relevant assumptions (which are necessarily verified by the $F_{t}$ ). In particular, if $F$ has covariance matrix $B$ and differentiable density $f$ then, letting $\rho_{F}(\mathbf{x}):=\nabla \log f(\mathbf{x})$ be the score function for $F$, the standardized Fisher information of $F$ is

$$
\begin{equation*}
J_{s t}(F)=B E\left[\rho_{F}(F) \rho_{F}(F)^{T}\right] . \tag{2.34}
\end{equation*}
$$

In the event that the above be well-defined then it is also scale invariant in the sense that $J_{s t}(\alpha F)=J_{s t}(F)$ for all $\alpha \in \mathbb{R}$.

The following fundamental result is known as the (multidimensional) de Bruijn's identity: it shows that the relative entropy $D(F \| Z)$ can be represented in terms of the integral of the mapping $t \mapsto \operatorname{tr}\left(C \Gamma_{t}^{-1} J_{s t}\left(F_{t}\right)\right)$ with respect to the measure $d t / 2 t$ on $(0,1]$. It is one of the staples of the entire paper. We refer the reader e.g. to $[1,8]$ for proofs in the case $d=1$. Our multidimensional statement is a rescaling of [23, Theorem 2.3] (some more details are given in the proof). See also [12].

Lemma 2.3 (Multivariate de Bruijn's identity). Let the above notation and assumptions prevail. Then,

$$
\begin{align*}
D(F \| Z)= & \int_{0}^{1} \frac{1}{2 t} \operatorname{tr}\left(C \Gamma_{t}^{-1} J_{s t}\left(F_{t}\right)\right) d t \\
& +\frac{1}{2}\left(\operatorname{tr}\left(C^{-1} B\right)-d\right)+\int_{0}^{1} \frac{1}{2 t} \operatorname{tr}\left(C \Gamma_{t}^{-1}-I_{d}\right) d t \tag{2.35}
\end{align*}
$$

Proof. In [23, Theorem 2.3] it is proved that

$$
\begin{aligned}
D(F \| Z)= & \int_{0}^{\infty} \frac{1}{2} \operatorname{tr}\left(C(B+\tau C)^{-1} J_{s t}(F+\sqrt{\tau} Z)\right) d \tau \\
& +\frac{1}{2}\left(\operatorname{tr}\left(C^{-1} B\right)-d\right)+\frac{1}{2} \int_{0}^{\infty} \operatorname{tr}\left(C\left((B+\tau C)^{-1}-\frac{C^{-1}}{1+\tau}\right)\right) d \tau
\end{aligned}
$$

(note that the definition of standardized Fisher information used in [23] is different from ours). The conclusion is obtained by using the change of variables $t=(1+\tau)^{-1}$, as well as the fact that

$$
J_{s t}\left(F+\sqrt{\frac{1-t}{t}} Z\right)=J_{s t}(\sqrt{t} F+\sqrt{1-t} Z)
$$

which follows from the scale-invariance of standardized Fisher information mentioned in Remark 2.2.

Remark 2.4. Assume that $C_{n}, n \geqslant 1$, is a sequence of $d \times d$ nonsingular covariance matrices such that $C_{n ; i, j} \rightarrow B_{i, j}$ for every $i, j=1, \ldots, d$, as $n \rightarrow \infty$. Then, the second and third summands of (2.35) (with $C_{n}$ replacing $C$ ) converge to 0 as $n \rightarrow \infty$.

For future reference, we will now rewrite formula (2.35) for some specific choices of $d, F, B$ and $C$.

## Example 2.5.

(i) Assume $F \sim \mathscr{N}_{d}(0, B)$. Then, $J_{s t}\left(F_{t}\right)=0$ (null matrix) for every $t \in[0,1)$, and formula (2.35) becomes

$$
\begin{equation*}
D(F \| Z)=\frac{1}{2}\left(\operatorname{tr}\left(C^{-1} B\right)-d\right)+\int_{0}^{1} \frac{1}{2 t} \operatorname{tr}\left(C \Gamma_{t}^{-1}-I_{d}\right) d t \tag{2.36}
\end{equation*}
$$

(ii) Assume that $d=1$ and that $F$ and $Z$ have variances $b, c>0$, respectively. Defining $\gamma_{t}=$ $t b+(1-t) c$, relation (2.35) becomes

$$
\begin{align*}
D(F \| Z) & =\int_{0}^{1} \frac{c}{2 t \gamma_{t}} J_{s t}\left(F_{t}\right) d t+\frac{1}{2}\left(\frac{b}{c}-1\right)+\int_{0}^{1} \frac{1}{2 t}\left(\frac{c}{\gamma_{t}}-1\right) d t \\
& =\int_{0}^{1} \frac{c}{2 t} E\left[\left(\rho_{t}\left(F_{t}\right)+\gamma_{t}^{-1} F_{t}\right)^{2}\right] d t+\frac{1}{2}\left(\frac{b}{c}-1\right)+\frac{\log c-\log b}{2} . \tag{2.37}
\end{align*}
$$

Relation (2.37) in the case $b=c\left(=\gamma_{t}\right)$ corresponds to the integral formula (1.12) proved by Barron in [8, Lemma 1].
(iii) If $B=C$, then (2.35) takes the form

$$
\begin{equation*}
D(F \| Z)=\int_{0}^{1} \frac{1}{2 t} \operatorname{tr}\left(J_{s t}\left(F_{t}\right)\right) d t \tag{2.38}
\end{equation*}
$$

In the special case where $B=C=I_{d}$, one has that

$$
\begin{equation*}
D(F \| Z)=\frac{1}{2} \sum_{j=1}^{d} \int_{0}^{1} \frac{1}{t} E\left[\left(\rho_{t, j}\left(F_{t}\right)+F_{t, j}\right)^{2}\right] d t \tag{2.39}
\end{equation*}
$$

of which (1.12) is a particular case $(d=1)$.
In the univariate setting, the general variance case $\left(E\left[F^{2}\right]=\sigma^{2}\right.$ ) follows trivially from the standardized one ( $E\left[F^{2}\right]=1$ ) through scaling; the same cannot be said in the multivariate setting since the appealing form (2.39) cannot be directly achieved for $d \geqslant 2$ when the covariance matrices are not the identity because here the dependence structure of $F$ needs to be taken into account. In Lemma 2.6 we provide an estimate allowing one to deal with this difficulty in the case $B=C$, for every $d$. The proof is based on the following elementary fact: if $A, B$ are two $d \times d$ symmetric matrices, and if $A$ is semi-positive definite, then

$$
\begin{equation*}
\lambda_{\min }(B) \times \operatorname{tr}(A) \leqslant \operatorname{tr}(A B) \leqslant \lambda_{\max }(B) \times \operatorname{tr}(A) \tag{2.40}
\end{equation*}
$$

where $\lambda_{\min }(B)$ and $\lambda_{\max }(B)$ stand, respectively, for the maximum and minimum eigenvalue of $B$. Observe that $\lambda_{\max }(B)=\|B\|_{o p}$, the operator norm of $B$.

Lemma 2.6. Fix $d \geqslant 1$, and assume that $B=C$. Then, $C \Gamma_{t}^{-1}=I_{d}$, and one has the following estimates

$$
\begin{align*}
& \lambda_{\min }(C) \times \sum_{j=1}^{d} E\left[\left(\rho_{t, j}\left(F_{t}\right)+\left(C^{-1} F_{t}\right)_{j}\right)^{2}\right] \\
& \quad \leqslant \operatorname{tr}\left(J_{s t}\left(F_{t}\right)\right) \\
& \quad \leqslant \lambda_{\max }(C) \times \sum_{j=1}^{d} E\left[\left(\rho_{t, j}\left(F_{t}\right)+\left(C^{-1} F_{t}\right)_{j}\right)^{2}\right]  \tag{2.41}\\
& \quad \lambda_{\min }\left(C^{-1}\right) \times \sum_{j=1}^{d} E\left[\left(\rho_{t, j}^{\star}\left(F_{t}\right)+F_{t, j}\right)^{2}\right] \\
& \quad \leqslant \operatorname{tr}\left(J_{s t}\left(F_{t}\right)\right) \\
& \quad \leqslant \lambda_{\max }\left(C^{-1}\right) \times \sum_{j=1}^{d} E\left[\left(\rho_{t, j}^{\star}\left(F_{t}\right)+F_{t, j}\right)^{2}\right] \tag{2.42}
\end{align*}
$$

Proof. Write $\operatorname{tr}\left(J_{s t}\left(F_{t}\right)\right)=\operatorname{tr}\left(C^{-1} J_{s t}\left(F_{t}\right) C\right.$ ) and apply (2.40) first to $A=C^{-1} J_{s t}\left(F_{t}\right)$ and $B=C$, and then to $A=J_{s t}\left(F_{t}\right) C$ and $B=C^{-1}$.

In the next section, we prove a new representation of the quantity $\rho_{t}\left(F_{t}\right)+C^{-1} F_{t}$ in terms of Stein matrices: this connection will provide the ideal framework in order to deal with the normal approximation of general random vectors.

### 2.3. Stein matrices and a key lemma

The centered $d$-dimensional vectors $F, Z$ are defined as in the previous section (in particular, they are stochastically independent).

Definition 2.7 (Stein matrices). Let $M(d, \mathbb{R})$ denote the space of $d \times d$ real matrices. We say that the matrix-valued mapping

$$
\tau_{F}: \mathbb{R}^{d} \rightarrow M(d, \mathbb{R}): \quad \mathbf{x} \mapsto \tau_{F}(\mathbf{x})=\left\{\tau_{F}^{i, j}(\mathbf{x}): i, j=1, \ldots, d\right\}
$$

is a Stein matrix for $F$ if $\tau_{F}^{i, j}(F) \in L^{1}$ for every $i, j$ and the following equality is verified for every differentiable function $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$ such that both sides are well-defined:

$$
\begin{equation*}
E[F g(F)]=E\left[\tau_{F}(F) \nabla g(F)\right], \tag{2.43}
\end{equation*}
$$

or, equivalently,

$$
\begin{equation*}
E\left[F_{i} g(F)\right]=\sum_{j=1}^{d} E\left[\tau_{F}^{i, j}(F) \partial_{j} g(F)\right], \quad i=1, \ldots, d \tag{2.44}
\end{equation*}
$$

The entries of the random matrix $\tau_{F}(F)$ are called the Stein factors of $F$.

## Remark 2.8.

(i) Selecting $g(F)=F_{j}$ in (2.43), one deduces that, if $\tau_{F}$ is a Stein matrix for $F$, then $E\left[\tau_{F}(F)\right]=B$. More to this point, if $F \sim \mathscr{N}_{d}(0, B)$, then the covariance matrix $B$ is itself a Stein matrix for $F$. This last relation is known as the Stein's identity for the multivariate Gaussian distribution.
(ii) Assume that $d=1$ and that $F$ has density $f$ and variance $b>0$. Then, under some standard regularity assumptions, it is easy to see that $\tau_{F}(x)=b \int_{x}^{\infty} y f(y) d y / f(x)$ is a Stein factor for $F$.

Lemma 2.9 (Key lemma). Let the above notation and framework prevail, and assume that $\tau_{F}$ is a Stein matrix for $F$ such that $\tau_{F}^{i, j}(F) \in L^{1}(\Omega)$ for every $i, j=1, \ldots, d$. Then, for every $t \in[0,1)$, the mapping

$$
\begin{equation*}
\mathbf{x} \mapsto-\frac{t}{\sqrt{1-t}} E\left[\left(I_{d}-C^{-1} \tau_{F}(F)\right) C^{-1} Z \mid F_{t}=\mathbf{x}\right]-C^{-1} \mathbf{x} \tag{2.45}
\end{equation*}
$$

is a version of the score $\rho_{t}$ of $F_{t}$. Also, the mapping

$$
\begin{equation*}
\mathbf{x} \mapsto-\frac{t}{\sqrt{1-t}} E\left[\left(\Gamma_{t}-\Gamma_{t} C^{-1} \tau_{F}(F)\right) C^{-1} Z \mid F_{t}=\mathbf{x}\right]-\Gamma_{t} C^{-1} \mathbf{x} \tag{2.46}
\end{equation*}
$$

is a version of the function $\rho_{t}^{\star}$ defined in formula (2.32).
Proof. Remember that $-C^{-1} Z$ is the score of $Z$, and denote by $\mathbf{x} \mapsto A_{t}(\mathbf{x})$ the mapping defined in (2.45). Removing the conditional expectation and exploiting the independence of $F$ and $Z$, we infer that, for every smooth test function $g$,

$$
\begin{aligned}
E\left[A_{t}\left(F_{t}\right) g\left(F_{t}\right)\right]= & \frac{t}{\sqrt{1-t}} E\left[\left(I_{d}-C^{-1} \tau_{F}(F)\right)\left(-C^{-1} Z\right) g\left(F_{t}\right)\right] \\
& -\sqrt{t} C^{-1} E\left[F g\left(F_{t}\right)\right]-\sqrt{1-t} E\left[C^{-1} Z g\left(F_{t}\right)\right] \\
= & -t E\left[\left(I_{d}-C^{-1} \tau_{F}(F)\right) \nabla g\left(F_{t}\right)\right] \\
& -t C^{-1} E\left[\tau_{F}(F) \nabla g\left(F_{t}\right)\right]-(1-t) E\left[\nabla g\left(F_{t}\right)\right] \\
= & -E\left[\nabla g\left(F_{t}\right)\right],
\end{aligned}
$$

thus yielding the desired conclusion.
To simplify the forthcoming discussion, we shall use the shorthand notation: $\widetilde{Z}=\left(\widetilde{Z}_{1}, \ldots\right.$, $\left.\widetilde{Z}_{d}\right):=C^{-1} Z \sim \mathscr{N}_{d}\left(0, C^{-1}\right), \widetilde{F}=\left(\widetilde{F}_{1}, \ldots, \widetilde{F}_{d}\right):=C^{-1} F$, and $\widetilde{\tau}_{F}=\left\{\widetilde{\tau}_{F}^{i, j}: i, j=1, \ldots, d\right\}:=$ $C^{-1} \tau_{F}$. The following statement is the main achievement of the section, and is obtained by combining Lemma 2.9 with formulae (2.38) and (2.41)-(2.42), in the case where $C=B$.

Theorem 2.10. Let the above notation and assumptions prevail, assume that $B=C$, and introduce the notation

$$
\begin{align*}
& A_{1}(F ; Z):=\frac{1}{2} \int_{0}^{1} \frac{t}{1-t} E\left[\sum_{j=1}^{d} E\left[\sum_{k=1}^{d}\left(\mathbf{1}_{j=k}-\widetilde{\tau}_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]^{2}\right] d t,  \tag{2.47}\\
& A_{2}(F ; Z):=\frac{1}{2} \int_{0}^{1} \frac{t}{1-t} E\left[\sum_{j=1}^{d} E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]^{2}\right] d t . \tag{2.48}
\end{align*}
$$

Then one has the inequalities

$$
\begin{align*}
& \lambda_{\text {min }}(C) \times A_{1}(F ; Z) \leqslant D(F \| Z) \leqslant \lambda_{\max }(C) \times A_{1}(F ; Z),  \tag{2.49}\\
& \lambda_{\text {min }}\left(C^{-1}\right) \times A_{2}(F ; Z) \leqslant D(F \| Z) \leqslant \lambda_{\max }\left(C^{-1}\right) \times A_{2}(F ; Z) . \tag{2.50}
\end{align*}
$$

In particular, when $C=B=I_{d}$,

$$
\begin{equation*}
D(F \| Z)=\frac{1}{2} \int_{0}^{1} \frac{t}{1-t} E\left[\sum_{j=1}^{d} E\left[\sum_{k=1}^{d}\left(\mathbf{1}_{j=k}-\tau_{F}^{j, k}(F)\right) Z_{k} \mid F_{t}\right]^{2}\right] d t \tag{2.51}
\end{equation*}
$$

The next subsection focuses on general bounds based on the estimates (2.47)-(2.51).

### 2.4. A general bound

The following statement provides the announced multidimensional generalization of Theorem 1.7. In particular, the main estimate (2.55) provides an explicit quantitative counterpart to the heuristic fact that, if there exists a Stein matrix $\tau_{F}$ such that $\left\|\tau_{F}-C\right\|_{H . S}$ is small (with $\|\cdot\|_{\text {H.S. }}$ denoting the usual Hilbert-Schmidt norm), then the distribution of $F$ and $Z \sim \mathscr{N}_{d}(0, C)$ must be close. By virtue of Theorem 2.10, the proximity of the two distributions is expressed in terms of the relative entropy $D(F \| Z)$.

Theorem 2.11. Let $F$ be a centered and square integrable random vector with density $f: \mathbb{R}^{d} \rightarrow$ $[0, \infty)$, let $C>0$ be its covariance matrix, and assume that $\tau_{F}$ is a Stein matrix for $F$. Let $Z \sim$ $\mathscr{N}_{d}(0, C)$ be a Gaussian random vector independent of $F$. If, for some $\kappa, \eta>0$ and $\alpha \in\left(0, \frac{1}{2}\right]$, one has

$$
\begin{equation*}
E\left[\left|\tau_{F}^{j, k}(F)\right|^{\eta+2}\right]<\infty, \quad j, k=1, \ldots, d \tag{2.52}
\end{equation*}
$$

as well as

$$
\begin{equation*}
\mathbf{T V}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}, F) \leqslant \kappa\left(1+\|\mathbf{x}\|_{1}\right)(1-t)^{\alpha}, \quad \mathbf{x} \in \mathbb{R}^{d}, t \in[1 / 2,1] \tag{2.53}
\end{equation*}
$$

then, provided

$$
\begin{equation*}
\Delta:=E\left[\left\|C-\tau_{F}\right\|_{H . S .}^{2}\right]=\sum_{j, k=1}^{d} E\left[\left(C(j, k)-\tau_{F}^{j, k}(F)\right)^{2}\right] \leqslant 2^{-\frac{\eta+1}{\alpha \eta}} \tag{2.54}
\end{equation*}
$$

one has

$$
\begin{align*}
D(F \| Z) \leqslant & \frac{d(\eta+1) \lambda_{\max }\left(C^{-1}\right)}{2 \alpha \eta} \max _{1 \leqslant l \leqslant d} E\left[\left(\widetilde{Z}_{l}\right)^{2}\right] \times \Delta|\log \Delta| \\
& +\frac{C_{d, \eta, \tau}(\eta+1) \lambda_{\max }\left(C^{-1}\right)}{2 \alpha \eta} \Delta \tag{2.55}
\end{align*}
$$

where

$$
\begin{align*}
C_{d, \eta, \tau}:= & 2 d^{2}\left(2 \kappa E\left[\|Z\|_{1}\left(1+\|Z\|_{1}\right)\right]+\sqrt{\max _{j} C(j, j)}\right) \max _{1 \leqslant l \leqslant d} E\left[\left|\widetilde{Z}_{l}\right|^{\eta+2}\right]^{\frac{1}{\eta+1}} \\
& \times \sum_{j, k=1}^{d}\left(|C(j, k)|^{\eta+2}+E\left[\left|\tau_{F}^{j, k}(F)\right|^{\eta+2}\right]\right)^{\frac{1}{\eta+1}} \tag{2.56}
\end{align*}
$$

and (as above) $\widetilde{Z}=C^{-1} Z$.

Proof. Take $g \in C_{c}^{1}$ such that $\|g\|_{\infty} \leqslant 1$. Then, by independence of $\widetilde{Z}$ and $F$ and using (2.44), one has, for any $j=1, \ldots, d$,

$$
\begin{aligned}
E & {\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} g\left(F_{t}\right)\right] } \\
& =\sum_{k, l=1}^{d} C(j, k) C^{-1}(k, l) E\left[Z_{l} g\left(F_{t}\right)\right]-\sum_{k, l=1}^{d} C^{-1}(k, l) E\left[\tau_{F}^{j, k}(F) Z_{l} g\left(F_{t}\right)\right] \\
& =E\left[Z_{j} g\left(F_{t}\right)\right]-\sqrt{1-t} \sum_{k, l, m=1}^{d} C^{-1}(k, l) C(l, m) E\left[\tau_{F}^{j, k}(F) \partial_{m} g\left(F_{t}\right)\right] \\
& =E\left[Z_{j}\left(g\left(F_{t}\right)-g(F)\right)\right]-\sqrt{1-t} \sum_{k=1}^{d} E\left[\tau_{F}^{j, k}(F) \partial_{k} g\left(F_{t}\right)\right] \\
& =E\left[Z_{j}\left(g\left(F_{t}\right)-g(F)\right)\right]-\sqrt{\frac{1-t}{t}} E\left[F_{j} g\left(F_{t}\right)\right]
\end{aligned}
$$

Using (2.53), we have

$$
\begin{aligned}
& \mid E {\left[Z_{j}\left(g\left(F_{t}\right)-g(F)\right)\right] \mid } \\
&=\left|\int_{\mathbb{R}^{d}} x_{j} E[g(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-g(F)] \frac{e^{-\frac{1}{2}\left\langle C^{-1} \mathbf{x}, \mathbf{x}\right\rangle}}{(2 \pi)^{\frac{d}{2}} \sqrt{\operatorname{det} C}} d \mathbf{x}\right| \\
& \leqslant 2 \int_{\mathbb{R}^{d}}\left|x_{j}\right| \mathbf{T V}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}, F) \frac{e^{-\frac{1}{2}\left\langle C^{-1} \mathbf{x}, \mathbf{x}\right\rangle}}{(2 \pi)^{\frac{d}{2}} \sqrt{\operatorname{det} C}} d \mathbf{x} \\
& \leqslant 2 \kappa(1-t)^{\alpha} \int_{\mathbb{R}^{d}}\|\mathbf{x}\|_{1}\left(1+\|\mathbf{x}\|_{1}\right) \frac{e^{-\frac{1}{2}\left\langle C^{-1} \mathbf{x}, \mathbf{x}\right\rangle}}{(2 \pi)^{\frac{d}{2}} \sqrt{\operatorname{det} C}} d \mathbf{x} \\
& \quad=2 \kappa E\left[\|Z\|_{1}\left(1+\|Z\|_{1}\right)\right](1-t)^{\alpha} .
\end{aligned}
$$

As a result, due to Lemma 1.5 and since $E\left|F_{j}\right| \leqslant \sqrt{E\left[F_{j}^{2}\right]} \leqslant \sqrt{\max _{j} C(j, j)}$, one obtains

$$
\begin{aligned}
& \max _{1 \leqslant j \leqslant d} E\left[\left|E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]\right|\right] \\
& \quad \leqslant\left(2 \kappa E\left[\|Z\|_{1}\left(1+\|Z\|_{1}\right)\right]+\sqrt{\max _{j} C(j, j)}\right)(1-t)^{\alpha} .
\end{aligned}
$$

Now, using among others the Hölder inequality and the convexity of the function $x \mapsto|x|^{\eta+2}$, we have that

$$
\begin{align*}
\sum_{j=1}^{d} E & {\left[E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]^{2}\right] } \\
= & \sum_{j=1}^{d} E\left[\left|E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]\right|^{\frac{\eta}{\eta+1}}\right. \\
& \left.\times\left|E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]\right|^{\frac{\eta+2}{\eta+1}}\right] \\
\leqslant & \sum_{j=1}^{d} E\left[\left|E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]\right|\right]^{\frac{\eta}{n+1}} \\
& \times E\left[\left|E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]\right|^{\eta+2}\right]^{\frac{1}{n+1}} \\
\leqslant & C_{d, \eta, \tau}(1-t)^{\frac{\alpha \eta}{\eta+1}}, \tag{2.57}
\end{align*}
$$

with $C_{d, \eta, \tau}$ given by (2.56). At this stage, we shall use the key identity (2.50). To properly control the right-hand side of (2.48), we split the integral in two parts: for every $0<\varepsilon \leqslant \frac{1}{2}$,

$$
\begin{aligned}
& \frac{2}{\lambda_{\max }\left(C^{-1}\right)} D(F \| Z) \\
& \leqslant \sum_{j=1}^{d} E\left[\left(\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k}\right)^{2}\right] \int_{0}^{1-\varepsilon} \frac{t d t}{1-t} \\
& \quad+\int_{1-\varepsilon}^{1} \frac{t}{1-t} \sum_{j=1}^{d} E\left[E\left[\sum_{k=1}^{d}\left(C(j, k)-\tau_{F}^{j, k}(F)\right) \widetilde{Z}_{k} \mid F_{t}\right]^{2}\right] d t \\
& \leqslant \\
& \quad \max _{1 \leqslant l \leqslant d} E\left[\left(\widetilde{Z}_{l}\right)^{2}\right] \sum_{j, k=1}^{d} E\left[\left(C(j, k)-\tau_{F}^{j, k}(F)\right)^{2}\right]|\log \varepsilon| \\
& \quad+C_{d, \eta, \tau} \int_{1-\varepsilon}^{1}(1-t)^{\frac{\alpha \eta}{\eta+1}-1} d t \\
& \leqslant \\
& \quad \max _{1 \leqslant l \leqslant d} E\left[\left(\widetilde{Z}_{l}\right)^{2}\right] \sum_{j, k=1}^{d} E\left[\left(C(j, k)-\tau_{F}^{j, k}(F)\right)^{2}\right]|\log \varepsilon|+C_{d, \eta, \tau} \frac{\eta+1}{\alpha \eta} \varepsilon^{\frac{\alpha \eta}{\eta+1}},
\end{aligned}
$$

the second inequality being a consequence of (2.57) as well as $\int_{0}^{1-\varepsilon} \frac{t d t}{1-t}=\int_{\varepsilon}^{1} \frac{(1-u) d u}{u} \leqslant \int_{\varepsilon}^{1} \frac{d u}{u}=$ $-\log \varepsilon$. Since (2.54) holds true, one can optimize over $\varepsilon$ and choose $\varepsilon=\Delta^{\frac{\eta+1}{\alpha \eta}}$, which leads to the desired estimate (2.55).

### 2.5. A general roadmap for proving quantitative entropic CLTs

In Section 4, we will apply the content of Theorem 2.11 to deduce entropic fourth moment theorems on a Gaussian space. As demonstrated in the discussion to follow, this achievement is just one possible application of a general strategy, leading to effective entropic estimates by means of Theorem 2.11.

Description of the strategy. Fix $d \geqslant 1$, and consider a sequence $F_{n}=\left(F_{1, n}, \ldots, F_{d, n}\right), n \geqslant 1$, of centered random vectors with covariance $C_{n}>0$ and such that $F_{n}$ has a density for every $n$. Let $Z_{n} \sim \mathscr{N}_{d}\left(0, C_{n}\right), n \geqslant 1$, be a sequence of Gaussian vectors, and assume that $C_{n} \rightarrow C>0$, as $n \rightarrow \infty$. Then, in order to show that $D\left(F_{n} \| Z_{n}\right) \rightarrow 0$ one has to accomplish the following steps:
(a) Write explicitly the Stein matrix $\tau_{F_{n}}$ for every $n$. This task can be realized either by exploiting the explicit form of the density of $F_{n}$, or by applying integration by parts formulae, whenever they are available. This latter case often leads to a representation of the Stein matrix by means of a conditional expectation. As an explicit example and as shown in Section 3.3 below, Stein matrices on a Gaussian space can be easily expressed in terms of Malliavin operators.
(b) Check that, for some $\eta>0$, the quantity $E\left[\left|\tau_{F_{n}}^{j, k}\left(F_{n}\right)\right|^{\eta+2}\right]$ is bounded by a finite constant independent of $n$. This step typically requires one to show that the sequence $\left\{\tau_{F_{n}}^{j, k}\left(F_{n}\right): n \geqslant 1\right\}$ is bounded in $L^{2}(\Omega)$, and moreover that the elements of this sequence verify some adequate hypercontractivity property. We will see in Section 4 that, when considering random variables living inside a finite sum of Wiener chaoses, these properties are implied by the explicit representation of Stein matrices in terms of Malliavin operators, as well as by the fundamental inequality stated in Proposition 3.4.
(c) Prove a total variation bound such as (2.53) for every $F_{n}$, with a constant $\kappa$ independent of $n$. This is arguably the most delicate step, as it consists in an explicit estimate of the total variation distance between the law of $F_{n}$ and that of $\sqrt{t} F_{n}+\sqrt{1-t} \mathbf{x}$, when $t$ is close to one. It is an interesting remark that, for every $i=1, \ldots, d$ (as $t \rightarrow 1$ ), $E\left[\left(F_{i, n}-\left(\sqrt{t} F_{i, n}+\sqrt{1-t} x_{i}\right)\right)^{2}\right]=O(1-t)$, so that an estimate such as (2.53) basically requires one to explicitly relate the total variation and mean-square distances between $F_{n}$ and $\sqrt{t} F_{n}+\sqrt{1-t} \mathbf{x}$. We will see in Section 4 that, for random variables living inside a fixed sum of Wiener chaoses, adequate bounds of this type can be deduced by applying the Carbery-Wright inequalities [11], that we shall combine with the approach developed by Nourdin, Nualart and Poly in [33].
(d) Show that $E\left\|\tau_{F_{n}}-C_{n}\right\|^{2} \rightarrow 0$. This is realized by using the explicit representation of the Stein matrices $\tau_{F_{n}}$.

Once steps (a)-(d) are accomplished, an upper bound on the speed of convergence to zero of the sequence $D\left(F_{n} \| Z_{n}\right)$ can be deduced from (2.55), whereas the total variation distance between the laws of $F_{n}$ and $Z$ follows from the inequality

$$
\mathbf{T V}\left(F_{n}, Z\right) \leqslant \mathbf{T V}\left(F_{n}, Z_{n}\right)+\mathbf{T V}\left(Z, Z_{n}\right) \leqslant \frac{1}{\sqrt{2}}\left[\sqrt{D\left(F_{n} \| Z_{n}\right)}+\sqrt{D\left(Z \| Z_{n}\right)}\right]
$$

Note that the quantity $D\left(Z \| Z_{n}\right)$ can be assessed by using (2.36).

Before proceeding to the application of the above roadmap on Gaussian space we now first provide, in the forthcoming Section 3, the necessary preliminary results about Gaussian stochastic analysis.

## 3. Gaussian spaces and variational calculus

As announced, we shall now focus on random variables that can be written as functionals of a countable collection of independent and identically distributed Gaussian $\mathscr{N}(0,1)$ random variables, that we shall denote by

$$
\begin{equation*}
\mathbf{G}=\left\{G_{i}: i \geqslant 1\right\} . \tag{3.58}
\end{equation*}
$$

Note that our description of $\mathbf{G}$ is equivalent to saying that $\mathbf{G}$ is a Gaussian sequence such that $E\left[G_{i}\right]=0$ for every $i$ and $E\left[G_{i} G_{j}\right]=\mathbf{1}_{\{i=j\}}$. We will write $L^{2}(\sigma(\mathbf{G})):=L^{2}(P, \sigma(\mathbf{G}))$ to indicate the class of square-integrable (real-valued) random variables that are measurable with respect to the $\sigma$-field generated by $\mathbf{G}$.

The reader is referred e.g. to [36,42] for any unexplained definition or result appearing in the subsequent subsections.

### 3.1. Wiener chaos

We will now briefly introduce the notion of Wiener chaos.

## Definition 3.1 (Hermite polynomials and Wiener chaos).

1. The sequence of Hermite polynomials $\left\{H_{m}: m \geqslant 0\right\}$ is defined as follows: $H_{0}=1$, and, for $m \geqslant 1$,

$$
H_{m}(x)=(-1)^{m} e^{\frac{x^{2}}{2}} \frac{d^{m}}{d x^{m}} e^{-\frac{x^{2}}{2}}, \quad x \in \mathbb{R}
$$

It is a standard result that the sequence $\left\{(m!)^{-1 / 2} H_{m}: m \geqslant 0\right\}$ is an orthonormal basis of $L^{2}\left(\mathbb{R}, \phi_{1}(x) d x\right)$.
2. A multi-index $\alpha=\left\{\alpha_{i}: i \geqslant 1\right\}$ is a sequence of nonnegative integers such that $\alpha_{i} \neq 0$ only for a finite number of indices $i$. We use the symbol $\Lambda$ in order to indicate the collection of all multi-indices, and use the notation $|\alpha|=\sum_{i \geqslant 1} \alpha_{i}$, for every $\alpha \in \Lambda$.
3. For every integer $q \geqslant 0$, the $q$ th Wiener chaos associated with $\mathbf{G}$ is defined as follows: $C_{0}=\mathbb{R}$, and, for $q \geqslant 1, C_{q}$ is the $L^{2}(P)$-closed vector space generated by random variables of the type

$$
\begin{equation*}
\Phi(\alpha)=\prod_{i=1}^{\infty} H_{\alpha_{i}}\left(G_{i}\right), \quad \alpha \in \Lambda \text { and }|\alpha|=q \tag{3.59}
\end{equation*}
$$

It is easily seen that two random variables belonging to Wiener chaoses of different orders are orthogonal in $L^{2}(\sigma(\mathbf{G}))$. Moreover, since linear combinations of polynomials are dense in $L^{2}(\sigma(\mathbf{G}))$, one has that $L^{2}(\sigma(\mathbf{G}))=\bigoplus_{q \geqslant 0} C_{q}$, that is, any square-integrable functional of $\mathbf{G}$
can be written as an infinite sum, converging in $L^{2}$ and such that the $q$ th summand is an element of $C_{q}$. This orthogonal decomposition of $L^{2}(\sigma(\mathbf{G}))$ is customarily called the Wiener-Itô chaotic decomposition of $L^{2}(\sigma(\mathbf{G}))$.

It is often convenient to encode random variables in the spaces $C_{q}$ by means of increasing tensor powers of Hilbert spaces. To do this, introduce an (arbitrary) separable real Hilbert space $\mathfrak{H}$ having an orthonormal basis $\left\{e_{i}: i \geqslant 1\right\}$. For $q \geqslant 2$, denote by $\mathfrak{H}^{\otimes q}$ (resp. $\mathfrak{H}^{\odot q}$ ) the $q$ th tensor power (resp. symmetric tensor power) of $\mathfrak{H}$; write moreover $\mathfrak{H}^{\otimes 0}=\mathfrak{H}^{\odot 0}=\mathbb{R}$ and $\mathfrak{H}^{\otimes 1}=\mathfrak{H}^{\odot 1}=\mathfrak{H}$. With every multi-index $\alpha \in \Lambda$, we associate the tensor $e(\alpha) \in \mathfrak{H}^{\otimes|\alpha|}$ given by

$$
e(\alpha)=e_{i_{1}}^{\otimes \alpha_{i_{1}}} \otimes \cdots \otimes e_{i_{k}}^{\otimes \alpha_{i_{k}}}
$$

where $\left\{\alpha_{i_{1}}, \ldots, \alpha_{i_{k}}\right\}$ are the non-zero elements of $\alpha$. We also denote by $\tilde{e}(\alpha) \in \mathfrak{H}^{\odot|\alpha|}$ the canonical symmetrization of $e(\alpha)$. It is well known that, for every $q \geqslant 2$, the set $\{\tilde{e}(\alpha): \alpha \in \Lambda,|\alpha|=q\}$ is a complete orthogonal system in $\mathfrak{H}^{\odot q}$. For every $q \geqslant 1$ and every $h \in \mathfrak{H}^{\odot q}$ of the form $h=\sum_{\alpha \in \Lambda,|\alpha|=q} c_{\alpha} \tilde{e}(\alpha)$, we define

$$
\begin{equation*}
I_{q}(h)=\sum_{\alpha \in \Lambda,|\alpha|=q} c_{\alpha} \Phi(\alpha), \tag{3.60}
\end{equation*}
$$

where $\Phi(\alpha)$ is given in (3.59). Another classical result (see e.g. [36,42]) is that, for every $q \geqslant 1$, the mapping $I_{q}: \mathfrak{H}^{\odot q} \rightarrow C_{q}$ (as defined in (3.60)) is onto, and defines an isomorphism between $C_{q}$ and the Hilbert space $\mathfrak{H}^{\odot q}$, endowed with the modified norm $\sqrt{q!}\|\cdot\|_{\mathfrak{H}^{\otimes q}}$. This means that, for every $h, h^{\prime} \in \mathfrak{H}^{\odot q}, E\left[I_{q}(h) I_{q}\left(h^{\prime}\right)\right]=q!\left\langle h, h^{\prime}\right\rangle_{\mathfrak{H}^{\otimes q}}$.

Finally, we observe that one can reexpress the Wiener-Itô chaotic decomposition of $L^{2}(\sigma(\mathbf{G}))$ as follows: every $F \in L^{2}(\sigma(\mathbf{G}))$ admits a unique decomposition of the type

$$
\begin{equation*}
F=\sum_{q=0}^{\infty} I_{q}\left(h_{q}\right) \tag{3.61}
\end{equation*}
$$

where the series converges in $L^{2}(\mathbf{G})$, the symmetric kernels $h_{q} \in \mathfrak{H}^{\odot q}, q \geqslant 1$, are uniquely determined by $F$, and $I_{0}\left(h_{0}\right):=E[F]$. This also implies that

$$
E\left[F^{2}\right]=E[F]^{2}+\sum_{q=1}^{\infty} q!\left\|h_{q}\right\|_{\mathfrak{H}^{\otimes q}}^{2}
$$

### 3.2. The language of Malliavin calculus: chaoses as eigenspaces

We let the previous notation and assumptions prevail: in particular, we shall fix for the rest of the section a real separable Hilbert space $\mathfrak{H}$, and represent the elements of the $q$ th Wiener chaos of $\mathbf{G}$ in the form (3.60). In addition to the previously introduced notation, $L^{2}(\mathfrak{H}):=L^{2}(\sigma(\mathbf{G}) ; \mathfrak{H})$ indicates the space of all $\mathfrak{H}$-valued random elements $u$, that are measurable with respect to $\sigma(\mathbf{G})$ and verify the relation $E\left[\|u\|_{\mathfrak{H}}^{2}\right]<\infty$. Note that, as it is customary, $\mathfrak{H}$ is endowed with the Borel $\sigma$-field associated with the distance on $\mathfrak{H}$ given by $\left(h_{1}, h_{2}\right) \mapsto\left\|h_{1}-h_{2}\right\|_{\mathfrak{H}}$.

Let $\mathscr{S}$ be the set of all smooth cylindrical random variables of the form

$$
F=g\left(I_{1}\left(h_{1}\right), \ldots, I_{1}\left(h_{n}\right)\right)
$$

where $n \geqslant 1, g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a smooth function with compact support and $h_{i} \in \mathfrak{H}$. The Malliavin derivative of $F$ (with respect to $\mathbf{G}$ ) is the element of $L^{2}(\mathfrak{H})$ defined as

$$
D F=\sum_{i=1}^{n} \partial_{i} g\left(I_{1}\left(h_{1}\right), \ldots, I_{1}\left(h_{n}\right)\right) h_{i}
$$

By iteration, one can define the $m$ th derivative $D^{m} F$ (which is an element of $L^{2}\left(\mathfrak{H}^{\otimes m}\right)$ ) for every $m \geqslant 2$. For $m \geqslant 1, \mathbb{D}^{m, 2}$ denotes the closure of $\mathscr{S}$ with respect to the norm $\|\cdot\|_{m, 2}$, defined by the relation

$$
\|F\|_{m, 2}^{2}=E\left[F^{2}\right]+\sum_{i=1}^{m} E\left[\left\|D^{i} F\right\|_{\mathfrak{H}^{\otimes i}}^{2}\right]
$$

It is a standard result that a random variable $F$ as in (3.61) is in $\mathbb{D}^{m, 2}$ if and only if $\sum_{q \geqslant 1} q^{m} q!\left\|f_{q}\right\|_{\mathfrak{H}^{\otimes q}}^{2}<\infty$, from which one deduces that $\bigoplus_{k=0}^{q} C_{k} \in \mathbb{D}^{m, 2}$ for every $q, m \geqslant 1$. Also, $D I_{1}(h)=h$ for every $h \in \mathfrak{H}$. The Malliavin derivative $D$ satisfies the following chain rule: if $g: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is continuously differentiable and has bounded partial derivatives, and if $\left(F_{1}, \ldots, F_{n}\right)$ is a vector of elements of $\mathbb{D}^{1,2}$, then $g\left(F_{1}, \ldots, F_{n}\right) \in \mathbb{D}^{1,2}$ and

$$
\begin{equation*}
\operatorname{Dg}\left(F_{1}, \ldots, F_{n}\right)=\sum_{i=1}^{n} \partial_{i} g\left(F_{1}, \ldots, F_{n}\right) D F_{i} \tag{3.62}
\end{equation*}
$$

In what follows, we denote by $\delta$ the adjoint of the operator $D$, also called the divergence operator. A random element $u \in L^{2}(\mathfrak{H})$ belongs to the domain of $\delta$, written $\operatorname{Dom} \delta$, if and only if it satisfies

$$
\left|E\left[\langle D F, u\rangle_{\mathfrak{H}}\right]\right| \leqslant c_{u} \sqrt{E\left[F^{2}\right]} \quad \text { for any } F \in \mathscr{S}
$$

for some constant $c_{u}$ depending only on $u$. If $u \in \operatorname{Dom} \delta$, then the random variable $\delta(u)$ is defined by the duality relationship (customarily called "integration by parts formula"):

$$
\begin{equation*}
E[F \delta(u)]=E\left[\langle D F, u\rangle_{\mathfrak{H}}\right] \tag{3.63}
\end{equation*}
$$

which holds for every $F \in \mathbb{D}^{1,2}$. A crucial object for our discussion is the Ornstein-Uhlenbeck semigroup associated with $\mathbf{G}$.

Definition 3.2 (Ornstein-Uhlenbeck semigroup). Let $\mathbf{G}^{\prime}$ be an independent copy of $\mathbf{G}$, and denote by $E^{\prime}$ the mathematical expectation with respect to $\mathbf{G}^{\prime}$. For every $t \geqslant 0$ the operator $P_{t}: L^{2}(\sigma(\mathbf{G})) \rightarrow L^{2}(\sigma(\mathbf{G}))$ is defined as follows: for every $F(\mathbf{G}) \in L^{2}(\sigma(\mathbf{G}))$,

$$
P_{t} F(\mathbf{G})=E^{\prime}\left[F\left(e^{-t} \mathbf{G}+\sqrt{1-e^{-2 t}} \mathbf{G}^{\prime}\right)\right]
$$

in such a way that $P_{0} F(\mathbf{G})=F(\mathbf{G})$ and $P_{\infty} F(\mathbf{G})=E[F(\mathbf{G})]$. The collection $\left\{P_{t}: t \geqslant 0\right\}$ verifies the semigroup property $P_{t} P_{s}=P_{t+s}$ and is called the Ornstein-Uhlenbeck semigroup associated with $\mathbf{G}$.

The properties of the semigroup $\left\{P_{t}: t \geqslant 0\right\}$ that are relevant for our study are gathered together in the next statement.

## Proposition 3.3.

1. For every $t>0$, the eigenspaces of the operator $P_{t}$ coincide with the Wiener chaoses $C_{q}$, $q=0,1, \ldots$, the eigenvalue of $C_{q}$ being given by the positive constant $e^{-q t}$.
2. The infinitesimal generator of $\left\{P_{t}: t \geqslant 0\right\}$, denoted by $L$, acts on square-integrable random variables as follows: a random variable $F$ with the form (3.61) is in the domain of $L$, written Dom $L$, if and only if $\sum_{q \geqslant 1} q I_{q}\left(h_{q}\right)$ is convergent in $L^{2}(\sigma(\mathbf{G}))$, and in this case

$$
L F=-\sum_{q \geqslant 1} q I_{q}\left(h_{q}\right) .
$$

In particular, each Wiener chaos $C_{q}$ is an eigenspace of $L$, with eigenvalue equal to $-q$.
3. The operator $L$ verifies the following properties: (i) $\operatorname{Dom} L=\mathbb{D}^{2,2}$, and (ii) a random variable $F$ is in $\operatorname{Dom} L$ if and only if $F \in \operatorname{Dom} \delta D$ (i.e. $F \in \mathbb{D}^{1,2}$ and $D F \in \operatorname{Dom} \delta$ ), and in this case one has that $\delta(D F)=-L F$.

In view of the previous statement, it is immediate to describe the pseudo-inverse of $L$, denoted by $L^{-1}$, as follows: for every mean zero random variable $F=\sum_{q \geqslant 1} I_{q}\left(h_{q}\right)$ of $L^{2}(\sigma(\mathbf{G}))$, one has that

$$
L^{-1} F=\sum_{q \geqslant 1}-\frac{1}{q} I_{q}\left(h_{q}\right) .
$$

It is clear that $L^{-1}$ is an operator with values in $\mathbb{D}^{2,2}$.
For future reference, we record the following estimate involving random variables living in a finite sum of Wiener chaoses: it is a direct consequence of the hypercontractivity of the OrnsteinUhlenbeck semigroup - see e.g. in [36, Theorem 2.7.2 and Theorem 2.8.12].

Proposition 3.4 (Hypercontractivity). Let $q \geqslant 1$ and $1 \leqslant s<t<\infty$. Then, there exists a finite constant $c(s, t, q)<\infty$ such that, for every $F \in \bigoplus_{k=0}^{q} C_{k}$,

$$
\begin{equation*}
E\left[|F|^{t}\right]^{\frac{1}{t}} \leqslant c(s, t, q) E\left[|F|^{s}\right]^{\frac{1}{s}} . \tag{3.64}
\end{equation*}
$$

In particular, all $L^{p}$ norms, $p \geqslant 1$, are equivalent on a finite sum of Wiener chaoses.
Since we will systematically work on a fixed sum of Wiener chaoses, we will not need to specify the explicit value of the constant $c(s, t, q)$. See again [36], and the references therein, for more details.

Example 3.5. Let $W=\left\{W_{t}: t \geqslant 0\right\}$ be a standard Brownian motion, let $\left\{e_{j}: j \geqslant 1\right\}$ be an orthonormal basis of $L^{2}\left(\mathbb{R}_{+}, \mathscr{B}\left(\mathbb{R}_{+}\right), d t\right)=: L^{2}\left(\mathbb{R}_{+}\right)$, and define $G_{j}=\int_{0}^{\infty} e_{j}(t) d W_{t}$. Then, $\sigma(W)=\sigma(\mathbf{G})$, where $\mathbf{G}=\left\{G_{j}: j \geqslant 1\right\}$. In this case, the natural choice of a Hilbert space is $\mathfrak{H}=L^{2}\left(\mathbb{R}_{+}\right)$and one has the following explicit characterization of the Wiener chaoses associated with $W$ : for every $q \geqslant 1$, one has that $F \in C_{q}$ if and only if there exists a symmetric kernel $f \in L^{2}\left(\mathbb{R}_{+}^{q}\right)$ such that

$$
F=q!\int_{0}^{\infty} \int_{0}^{t_{1}} \cdots \int_{0}^{t_{q-1}} f\left(t_{1}, \ldots, t_{q}\right) d W_{t_{q}} \cdots d W_{t_{1}}:=q!J_{q}(f)
$$

The random variable $J_{q}(f)$ is called the multiple Wiener-Itô integral of order $q$, of $f$ with respect to $W$. It is a well-known fact that, if $F \in \mathbb{D}^{1,2}$ admits the chaotic expansion $F=E[F]+$ $\sum_{q \geqslant 1} J_{q}\left(f_{q}\right)$, then $D F$ equals the random function

$$
\begin{aligned}
t & \mapsto \sum_{q \geqslant 1} q J_{q-1}\left(f_{q}(t, \cdot)\right) \\
& =\sum_{q \geqslant 1} q!\int_{0}^{\infty} \int_{0}^{t_{1}} \cdots \int_{0}^{t_{q-2}} f\left(t, t_{1}, \ldots, t_{q-1}\right) d W_{t_{q-1}} \cdots d W_{t_{1}}, \quad t \in \mathbb{R}_{+}
\end{aligned}
$$

which is a well-defined element of $L^{2}(\mathfrak{H})$.

### 3.3. The role of Malliavin and Stein matrices

Given a vector $F=\left(F_{1}, \ldots, F_{d}\right)$ whose elements are in $\mathbb{D}^{1,2}$, we define the Malliavin matrix $\Gamma(F)=\left\{\Gamma_{i, j}(F): i, j=1, \ldots, d\right\}$ as

$$
\Gamma_{i, j}(F)=\left\langle D F_{i}, D F_{j}\right\rangle_{\mathfrak{H}} .
$$

The following statement is taken from [33], and provides a simple necessary and sufficient condition for a random vector living in a finite sum of Wiener chaoses to have a density.

Theorem 3.6. Fix $d, q \geqslant 1$ and let $F=\left(F_{1}, \ldots, F_{d}\right)$ be such that $F_{i} \in \bigoplus_{i=0}^{q} C_{i}, i=1, \ldots, d$. Then, the distribution of $F$ admits a density $f$ with respect to the Lebesgue measure on $\mathbb{R}^{d}$ if and only if $E[\operatorname{det} \Gamma(F)]>0$. Moreover, if this condition is verified one has necessarily that $\operatorname{Ent}(F)<\infty$.

Proof. The equivalence between the existence of a density and the fact that $E[\operatorname{det} \Gamma(F)]>0$ is shown in [33, Theorem 3.1]. Moreover, by [33, Theorem 4.2] we have in this case that the density $f$ satisfies $f \in \bigcup_{p>1} L^{p}\left(\mathbb{R}^{d}\right)$. Relying on the inequality

$$
\log u \leqslant n\left(u^{1 / n}-1\right), \quad u>0, n \in \mathbb{N}
$$

(which is a direct consequence of $\log u \leqslant u-1$ for any $u>0$ ), one has that

$$
\int_{\mathbb{R}^{d}} f(\mathbf{x}) \log f(\mathbf{x}) d \mathbf{x} \leqslant n\left(\int_{\mathbb{R}^{d}} f(\mathbf{x})^{1+\frac{1}{n}} d \mathbf{x}-1\right)
$$

Hence, by choosing $n$ large enough so that $f \in L^{1+\frac{1}{n}}\left(\mathbb{R}^{d}\right)$, one obtains that $\operatorname{Ent}(F)<\infty$.
To conclude, we present a result providing an explicit representation for Stein matrices associated with random vectors in the domain of $D$.

Proposition 3.7 (Representation of Stein matrices). Fix $d \geqslant 1$ and let $F=\left(F_{1}, \ldots, F_{d}\right)$ be a centered random vector whose elements are in $\mathbb{D}^{1,2}$. Then, a Stein matrix for $F$ (see Definition 2.7) is given by

$$
\tau_{F}^{i, j}(\mathbf{x})=E\left[\left\langle-D L^{-1} F_{i}, D F_{j}\right\rangle_{\mathfrak{H}} \mid F=\mathbf{x}\right], \quad i, j=1, \ldots, d
$$

Proof. Let $g: \mathbb{R}^{d} \rightarrow \mathbb{R} \in C_{c}^{1}$. For every $i=1, \ldots, d$, one has that $F_{i}=-\delta D L^{-1} F_{i}$. As a consequence, using (in order) (3.63) and (3.62), one infers that

$$
E\left[F_{i} g(F)\right]=E\left[\left\langle-D L^{-1} F_{i}, D g(F)\right\rangle_{\mathfrak{H}}\right]=\sum_{j=1}^{d} E\left[\left\langle-D L^{-1} F_{i}, D F_{j}\right\rangle_{\mathfrak{H}} \partial_{j} g(F)\right]
$$

Taking conditional expectations yields the desired conclusion.

The next section contains the statements and proofs of our main bounds on a Gaussian space.

## 4. Entropic fourth moment bounds on a Gaussian space

### 4.1. Main results

We let the framework of the previous section prevail: in particular, $\mathbf{G}$ is a sequence of i.i.d. $\mathscr{N}(0,1)$ random variables, and the sequence of Wiener chaoses $\left\{C_{q}: q \geqslant 1\right\}$ associated with $\mathbf{G}$ is encoded by means of increasing tensor powers of a fixed real separable Hilbert space $\mathfrak{H}$. We will use the following notation: given a sequence of centered and square-integrable $d$-dimensional random vectors $F_{n}=\left(F_{1, n}, \ldots, F_{d, n}\right) \in \mathbb{D}^{1,2}$ with covariance matrix $C_{n}, n \geqslant 1$, we let

$$
\begin{equation*}
\Delta_{n}:=E\left[\left\|F_{n}\right\|^{4}\right]-E\left[\left\|Z_{n}\right\|^{4}\right] \tag{4.65}
\end{equation*}
$$

where $\|\cdot\|$ is the Euclidean norm on $\mathbb{R}^{d}$ and $Z_{n} \sim \mathscr{N}_{d}\left(0, C_{n}\right)$.
Our main result is the following entropic central limit theorem for sequences of chaotic random variables.

Theorem 4.1 (Entropic CLTs on Wiener chaos). Let $d \geqslant 1$ and $q_{1}, \ldots, q_{d} \geqslant 1$ be fixed integers. Consider vectors

$$
F_{n}=\left(F_{1, n}, \ldots, F_{d, n}\right)=\left(I_{q_{1}}\left(h_{1, n}\right), \ldots, I_{q_{d}}\left(h_{d, n}\right)\right), \quad n \geqslant 1,
$$

with $h_{i, n} \in \mathfrak{H}^{\odot q_{i}}$. Let $C_{n}$ denote the covariance matrix of $F_{n}$ and let $Z_{n} \sim \mathscr{N}_{d}\left(0, C_{n}\right)$ be a centered Gaussian random vector in $\mathbb{R}^{d}$ with the same covariance matrix as $F_{n}$. Assume that $C_{n} \rightarrow C>0$ and $\Delta_{n} \rightarrow 0$, as $n \rightarrow \infty$. Then, the random vector $F_{n}$ admits a density for $n$ large enough, and

$$
\begin{equation*}
D\left(F_{n} \| Z_{n}\right)=O(1) \Delta_{n}\left|\log \Delta_{n}\right| \quad \text { as } n \rightarrow \infty \tag{4.66}
\end{equation*}
$$

where $O(1)$ indicates a bounded numerical sequence depending on $d, q_{1}, \ldots, q_{d}$, as well as on the sequence $\left\{F_{n}\right\}$.

One immediate consequence of the previous statement is the following characterization of entropic CLTs on a finite sum of Wiener chaoses.

Corollary 4.2. Let the sequence $\left\{F_{n}\right\}$ be as in the statement of Theorem 4.1, and assume that $C_{n} \rightarrow C>0$. Then, the following three assertions are equivalent, as $n \rightarrow \infty$ :
(i) $\Delta_{n} \rightarrow 0$;
(ii) $F_{n}$ converges in distribution to $Z \sim \mathscr{N}_{d}(0, C)$;
(iii) $D\left(F_{n} \| Z_{n}\right) \rightarrow 0$.

The proofs of the previous results are based on two technical lemmas that are the object of the next section.

### 4.2. Estimates based on the Carbery-Wright inequalities

We start with a generalization of the inequality proved by Carbery and Wright in [11]. Recall that, in a form that is adapted to our framework, the main finding of [11] reads as follows: there is a universal constant $c>0$ such that, for any polynomial $Q: \mathbb{R}^{n} \rightarrow \mathbb{R}$ of degree at most $d$ and any $\alpha>0$ we have

$$
\begin{equation*}
E\left[Q\left(X_{1}, \ldots, X_{n}\right)^{2}\right]^{\frac{1}{2 d}} P\left(\left|Q\left(X_{1}, \ldots, X_{n}\right)\right| \leqslant \alpha\right) \leqslant c d \alpha^{\frac{1}{d}} \tag{4.67}
\end{equation*}
$$

where $X_{1}, \ldots, X_{n}$ are independent random variables with common distribution $\mathscr{N}(0,1)$.
Lemma 4.3. Fix $d, q_{1}, \ldots, q_{d} \geqslant 1$, and let $F=\left(F_{1}, \ldots, F_{d}\right)$ be a random vector such that $F_{i}=I_{q_{i}}\left(h_{i}\right)$ with $h_{i} \in \mathfrak{H}^{\odot q_{i}}$. Let $\Gamma=\Gamma(F)$ denote the Malliavin matrix of $F$, and assume that $E[\operatorname{det} \Gamma]>0$ (which is equivalent to assuming that $F$ has a density by Theorem 3.6). Set $N=2 d(q-1)$ with $q=\max _{1 \leqslant i \leqslant d} q_{i}$. Then, there exists a universal constant $c>0$ such that

$$
\begin{equation*}
P(\operatorname{det} \Gamma \leqslant \lambda) \leqslant c N \lambda^{1 / N}(E[\operatorname{det} \Gamma])^{-1 / N} \tag{4.68}
\end{equation*}
$$

Proof. Let $\left\{e_{i}: i \geqslant 1\right\}$ be an orthonormal basis of $\mathfrak{H}$. Since det $\Gamma$ is a polynomial of degree $d$ in the entries of $\Gamma$ and because each entry of $\Gamma$ belongs to $\bigoplus_{k=0}^{2 q-2} C_{k}$ by the product formula for multiple integrals (see, e.g., [36, Chapter 2]), we have, by iterating the product formula, that $\operatorname{det} \Gamma \in \bigoplus_{k=0}^{N} C_{k}$. Thus, there exists a sequence $\left\{Q_{n}, n \geqslant 1\right\}$ of real-valued polynomials of degree at most $N$ such that the random variables $Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)$ converge in $L^{2}$ and almost surely to det $\Gamma$ as $n$ tends to infinity (see [40, proof of Theorem 3.1] for an explicit construction). Assume now that $E[\operatorname{det} \Gamma]>0$. Then, for $n$ sufficiently large, $E\left[\left|Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)\right|\right]>0$. We deduce from the estimate (4.67) the existence of a universal constant $c>0$ such that, for any $n \geqslant 1$,

$$
P\left(\left|Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)\right| \leqslant \lambda\right) \leqslant c N \lambda^{1 / N}\left(E\left[Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)^{2}\right]\right)^{-1 / 2 N}
$$

Using the property

$$
E\left[Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)^{2}\right] \geqslant\left(E\left[\left|Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)\right|\right]\right)^{2}
$$

we obtain

$$
P\left(\left|Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)\right| \leqslant \lambda\right) \leqslant c N \lambda^{1 / N}\left(E\left[\left|Q_{n}\left(I_{1}\left(e_{1}\right), \ldots, I_{1}\left(e_{n}\right)\right)\right|\right]\right)^{-1 / N}
$$

from which (4.68) follows by letting $n$ tend to infinity.
The next statement, whose proof follows the same lines than that of [33, Theorem 4.1], provides an upper bound on the total variation distance between the distribution of $F$ and that of $\sqrt{t} F+\sqrt{1-t} \mathbf{x}$, for every $\mathbf{x} \in \mathbb{R}^{d}$ and every $t \in[1 / 2 ; 1]$. Although Lemma 4.4 is, in principle, very close to [33, Theorem 4.1], we detail its proof because, here, we need to keep track of the way the constants behave with respect to $\mathbf{x}$.

Lemma 4.4. Fix $d, q_{1}, \ldots, q_{d} \geqslant 1$, and let $F=\left(F_{1}, \ldots, F_{d}\right)$ be a random vector as in Lemma 4.3. Set $q=\max _{1 \leqslant i \leqslant d} q_{i}$. Let $C$ be the covariance matrix of $F$, let $\Gamma=\Gamma(F)$ denote the Malliavin matrix of $F$, and assume that $\beta:=E[\operatorname{det} \Gamma]>0$. Then, there exists a constant $c_{q, d,\|C\|_{H . S}}>0$ (depending only on $q, d$ and $\|C\|_{H . S .}$ - with a continuous dependence in the last parameter) such that, for any $\mathbf{x} \in \mathbb{R}^{d}$ and $t \in\left[\frac{1}{2}, 1\right]$,

$$
\begin{align*}
& \mathbf{T V}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}, F) \\
& \quad \leqslant c_{q, d,\|C\|_{H . S}\left(\beta^{-\frac{1}{N+1}} \wedge 1\right)\left(1+\|\mathbf{x}\|_{1}\right)(1-t)^{\frac{1}{2(2 N+4)(d+1)+2}}} . \tag{4.69}
\end{align*}
$$

Here, $N=2 d(q-1)$.
Proof. The proof is divided into several steps. In what follows, we fix $t \in\left[\frac{1}{2}, 1\right]$ and $\mathbf{x} \in \mathbb{R}^{d}$ and we use the convention that $c_{\{\cdot\}}$ denotes a constant in $(0, \infty)$ that only depends on the arguments inside the bracket and whose value is allowed to change from one line to another.

Step 1. One has that $E\left[\|F\|_{\infty}^{2}\right] \leqslant c_{d} E\left[\|F\|_{2}^{2}\right] \leqslant c_{d} \sqrt{\sum_{i, j=1}^{d} C(i, i)^{2}} \leqslant c_{d}\|C\|_{H . S}$. so that $E\left[\|F\|_{\infty}\right] \leqslant c_{d} \sqrt{\|C\|_{H . S .}}=c_{d,\|C\|_{H . S}}$. Let $g: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a (smooth) test function bounded by 1 . We can write, for any $M \geqslant 1$,

$$
\begin{align*}
& \mid E[ g(\sqrt{t} F+\sqrt{1-t} \mathbf{x})]-E[g(F)] \mid \\
& \leqslant\left|E\left[\left(g \mathbf{1}_{[-M / 2, M / 2]^{d}}\right)(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right]-E\left[\left(g \mathbf{1}_{[-M / 2, M / 2]^{d}}\right)(F)\right]\right| \\
&+P\left(\|\sqrt{t} F+\sqrt{1-t} \mathbf{x}\|_{\infty} \geqslant M / 2\right)+P\left(\|F\|_{\infty} \geqslant M / 2\right) \\
& \leqslant \sup _{\|\phi\|_{\infty} \leqslant 1}|E[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})]-E[\phi(F)]| \\
& \quad \operatorname{supp} \phi \subset[-M, M]^{d} \\
&+\frac{2}{M}\left(E\left[\|\sqrt{t} F+\sqrt{1-t} \mathbf{x}\|_{\infty}\right]+E\left[\|F\|_{\infty}\right]\right) \\
& \leqslant \sup _{\|\phi\|_{\infty} \leqslant 1}|E[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})]-E[\phi(F)]| \\
& \quad \operatorname{supp} \phi \subset[-M, M]^{d}  \tag{4.70}\\
&+\frac{c_{d, \| C C}}{M}\left(1+\|\mathbf{x}\|_{\infty}\right) .
\end{align*}
$$

Step 2 . Let $\phi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be $\mathcal{C}^{\infty}$ with compact support in $[-M, M]^{d}$ and satisfying $\|\phi\|_{\infty} \leqslant 1$. Let $0<\alpha \leqslant 1$ and let $\rho: \mathbb{R}^{d} \rightarrow \mathbb{R}_{+}$be in $\mathcal{C}_{c}^{\infty}$ and satisfying $\int_{\mathbb{R}^{d}} \rho(x) d x=1$. Set $\rho_{\alpha}(x)=\frac{1}{\alpha^{d}} \rho\left(\frac{x}{\alpha}\right)$. By [40, formula (3.26)], we have that $\phi * \rho_{\alpha}$ is Lipschitz continuous with constant $1 / \alpha$. We can thus write,

$$
\begin{align*}
\mid E[ & \phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})]-E[\phi(F)] \mid \\
\leqslant & \left|E\left[\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(F)\right]\right|+\left|E\left[\phi(F)-\phi * \rho_{\alpha}(F)\right]\right| \\
& +\left|E\left[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right]\right| \\
\leqslant & \frac{\sqrt{1-t}}{\alpha}\left(E\left[\|F\|_{\infty}\right]+\|\mathbf{x}\|_{\infty}\right)+\left|E\left[\phi(F)-\phi * \rho_{\alpha}(F)\right]\right| \\
& +\left|E\left[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right]\right| \\
\leqslant & c_{d,\|C\|_{H . S}} \frac{\sqrt{1-t}}{\alpha}\left(1+\|\mathbf{x}\|_{1}\right)+\left|E\left[\phi(F)-\phi * \rho_{\alpha}(F)\right]\right| \\
& +\left|E\left[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right]\right| . \tag{4.71}
\end{align*}
$$

In order to estimate the two last terms in (4.71), we decompose the expectation into two parts using the identity

$$
1=\frac{\varepsilon}{t^{d} \operatorname{det} \Gamma+\varepsilon}+\frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}, \quad \varepsilon>0
$$

Step 3. For all $\varepsilon, \lambda>0$ and using (4.68),

$$
\begin{aligned}
E\left[\frac{\varepsilon}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right] & \leqslant E\left[\frac{\varepsilon}{t^{d} \operatorname{det} \Gamma+\varepsilon} \mathbf{1}_{\{\operatorname{det} \Gamma>\lambda\}}\right]+c N\left(\frac{\lambda}{E[\operatorname{det} \Gamma]}\right)^{1 / N} \\
& \leqslant \frac{\varepsilon}{t^{d} \lambda}+c N\left(\frac{\lambda}{\beta}\right)^{1 / N}
\end{aligned}
$$

Choosing $\lambda=\varepsilon^{\frac{N}{N+1}} \beta^{\frac{1}{N+1}}$ yields

$$
E\left[\frac{\varepsilon}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right] \leqslant\left(t^{-d}+c N\right)\left(\frac{\varepsilon}{\beta}\right)^{\frac{1}{N+1}} \leqslant c_{q, d}\left(\frac{\varepsilon}{\beta}\right)^{\frac{1}{N+1}} \quad\left(\text { recall that } t \geqslant \frac{1}{2}\right)
$$

As a consequence,

$$
\begin{align*}
\mid E & {\left[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right] \mid } \\
= & \mid E\left[\left(\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right)\right. \\
& \left.\times\left(\frac{\varepsilon}{t^{d} \operatorname{det} \Gamma+\varepsilon}+\frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right)\right] \mid \\
\leqslant & c_{q, d}\left(\frac{\varepsilon}{\beta}\right)^{\frac{1}{N+1}} \\
& +\left|E\left[\left(\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})-\phi * \rho_{\alpha}(\sqrt{t} F+\sqrt{1-t} \mathbf{x})\right) \frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right]\right| \tag{4.72}
\end{align*}
$$

Step 4. In this step we recall from [33, p. 11] the following integration by parts formula (4.73). Let $h: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a function in $\mathcal{C}^{\infty}$ with compact support, and consider a random variable $W \in \mathbb{D}^{\infty}$. Consider the Poisson kernel in $\mathbb{R}^{d}$, defined as the solution to the equation $\Delta Q_{d}=\delta_{0}$. We know that $Q_{2}(x)=c_{2} \log |x|$ and $Q_{d}(x)=c_{d}|x|^{2-d}$ for $d \neq 2$. We have the following identity

$$
\begin{align*}
& E {[W \operatorname{det} \Gamma h(\sqrt{t} F+\sqrt{1-t} \mathbf{x})] } \\
& \quad=\frac{1}{\sqrt{t}} \sum_{i=1}^{d} E\left[A_{i}(W) \int_{\mathbb{R}^{d}} h(y) \partial_{i} Q_{d}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}-y) d y\right], \tag{4.73}
\end{align*}
$$

where

$$
A_{i}(W)=-\sum_{a=1}^{d}\left(\left\langle D\left(W(\operatorname{Adj} \Gamma)_{a, i}\right), D F_{a}\right\rangle_{\mathfrak{H}}+(\operatorname{Adj} \Gamma)_{a, i} W L F_{a}\right)
$$

with Adj the usual adjugate matrix operator.
Step 5. Let us apply the identity (4.73) to the function $h=\phi-\phi * \rho_{\alpha}$ and to the random variable $W=W_{\varepsilon}=\frac{1}{t^{d} \operatorname{det} \Gamma+\varepsilon} \in \mathbb{D}^{\infty}$; we obtain

$$
\begin{align*}
& E\left[\left(\phi-\phi * \rho_{\alpha}\right)(\sqrt{t} F+\sqrt{1-t} \mathbf{x}) \frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right] \\
& \quad=t^{d-\frac{1}{2}} \sum_{i=1}^{d} E\left[A_{i}\left(W_{\varepsilon}\right) \int_{\mathbb{R}^{d}}\left(\phi-\phi * \rho_{\alpha}\right)(\mathbf{y}) \partial_{i} Q_{d}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}-\mathbf{y}) d \mathbf{y}\right] \tag{4.74}
\end{align*}
$$

From the hypercontractivity property together with the equality

$$
\begin{aligned}
A_{i}\left(W_{\varepsilon}\right)= & \sum_{a=1}^{d}\left\{-\frac{1}{t^{d} \operatorname{det} \Gamma+\varepsilon}\left(\left\langle D(\operatorname{Adj} \Gamma)_{a, i}, D F_{a}\right\rangle_{\mathfrak{H}}-(\operatorname{Adj} \Gamma)_{a, i} L F_{a}\right)\right. \\
& \left.+\frac{1}{\left(t^{d} \operatorname{det} \Gamma+\varepsilon\right)^{2}}(\operatorname{Adj} \Gamma)_{a, i}\left\langle D(\operatorname{det} \Gamma), D F_{a}\right\rangle_{\mathfrak{H}}\right\}
\end{aligned}
$$

one immediately deduces the existence of $c_{q, d,\|C\|_{H . S .}}>0$ such that

$$
E\left[A_{i}\left(W_{\varepsilon}\right)^{2}\right] \leqslant c_{q, d,\|C\|_{H . S}} \varepsilon^{-4}
$$

On the other hand, in [33, p. 13] it is shown that there exists $c_{d}>0$ such that, for any $R>0$ and $u \in \mathbb{R}^{d}$,

$$
\left|\int_{\mathbb{R}^{d}}\left(\phi-\phi * \rho_{\alpha}\right)(\mathbf{y}) \partial_{i} Q_{d}(\mathbf{u}-\mathbf{y}) d \mathbf{y}\right| \leqslant c_{d}\left(R+\alpha+\alpha R^{-d}\left(\|\mathbf{u}\|_{1}+M\right)^{d}\right) .
$$

Substituting this estimate into (4.74) and assuming that $M \geqslant 1$, yield

$$
\begin{aligned}
& \left|E\left[\left(\phi-\phi * \rho_{\alpha}\right)(\sqrt{t} F+\sqrt{1-t} \mathbf{x}) \frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right]\right| \\
& \quad \leqslant c_{q, d,\|C\|_{H . S} .} \varepsilon^{-2}\left(R+\alpha+\alpha R^{-d}\left(M+\|\mathbf{x}\|_{1}\right)^{d}\right) .
\end{aligned}
$$

Choosing $R=\alpha^{\frac{1}{d+1}}\left(M+\|\mathbf{x}\|_{1}\right)^{\frac{d}{d+1}}$ and assuming $\alpha \leqslant 1$, we obtain

$$
\begin{align*}
& \left|E\left[\left(\phi-\phi * \rho_{\alpha}\right)(\sqrt{t} F+\sqrt{1-t} \mathbf{x}) \frac{t^{d} \operatorname{det} \Gamma}{t^{d} \operatorname{det} \Gamma+\varepsilon}\right]\right| \\
& \quad \leqslant c_{q, d,\|C\|_{H . S} \varepsilon^{-2} \alpha^{\frac{1}{d+1}}\left(M+\|\mathbf{x}\|_{1}\right)^{\frac{d}{d+1}}} . \tag{4.75}
\end{align*}
$$

It is worthwhile noting that the inequality (4.75) is valid for any $t \in\left[\frac{1}{2}, 1\right]$, in particular for $t=1$.
Step 6. From (4.71), (4.72) and (4.75) we obtain

$$
\begin{aligned}
& |E[\phi(\sqrt{t} F+\sqrt{1-t} \mathbf{x})]-E[\phi(F)]| \\
& \leqslant \\
& \quad c_{d,\|C\|_{H . S} \frac{\sqrt{1-t}}{\alpha}\left(1+\|\mathbf{x}\|_{1}\right)+c_{q, d}\left(\frac{\varepsilon}{\beta}\right)^{\frac{1}{N+1}}} \quad+c_{q, d,\|C\|_{H . S}} \varepsilon^{-2} \alpha^{\frac{1}{d+1}}\left(M+\|\mathbf{x}\|_{1}\right)^{\frac{d}{d+1}} .
\end{aligned}
$$

By plugging this inequality into (4.70) we thus obtain that, for every $M \geqslant 1, \varepsilon>0$ and $0<\alpha \leqslant 1$ :

$$
\begin{align*}
& \mathbf{T V}(\sqrt{t} F+\sqrt{1-t} \mathbf{x}, F) \\
& \leqslant c_{d,\|C\|_{H . S .}} \frac{\sqrt{1-t}}{\alpha}\left(1+\|\mathbf{x}\|_{1}\right)+c_{q, d}\left(\frac{\varepsilon}{\beta}\right)^{\frac{1}{N+1}}+c_{q, d,\|C\|_{H . S .}} \varepsilon^{-2} \alpha^{\frac{1}{d+1}}\left(M+\|\mathbf{x}\|_{1}\right)^{\frac{d}{d+1}} \\
&+\frac{c_{d,\|C\|_{H . S}}^{M}}{M}\left(1+\|\mathbf{x}\|_{1}\right) \\
& \leqslant c_{q, d,\|C\|_{H . S}}\left(1+\|\mathbf{x}\|_{1}\right)\left(\beta^{-\frac{1}{N+1}} \wedge 1\right)\left\{\frac{\sqrt{1-t}}{\alpha}+\varepsilon^{\frac{1}{N+1}}+\frac{\alpha^{\frac{1}{d+1}} M}{\varepsilon^{2}}+\frac{1}{M}\right\} . \tag{4.76}
\end{align*}
$$

Choosing $M=\varepsilon^{-\frac{1}{N+1}}, \varepsilon=\alpha^{\frac{N+1}{(2 N+4)(d+1)}}$ and $\alpha=(1-t)^{\frac{(2 N+4)(d+1)}{2(2 N+4)(d+1)+1)}}$, one obtains the desired conclusion (4.69).

### 4.3. Proof of Theorem 4.1

In the proof of [41, Theorem 4.3], the following two facts have been shown:

$$
\begin{aligned}
E\left[\left(C_{n}(j, k)-\frac{1}{q_{j}}\left\langle D F_{j, n}, D F_{k, n}\right\rangle_{\mathfrak{H}}\right)^{2}\right] & \leqslant \operatorname{Cov}\left(F_{j, n}^{2}, F_{k, n}^{2}\right)-2 C_{n}(j, k)^{2} \\
E\left[\left\|F_{n}\right\|^{4}\right]-E\left[\left\|Z_{n}\right\|^{4}\right] & =\sum_{j, k=1}^{d}\left\{\operatorname{Cov}\left(F_{j, n}^{2}, F_{k, n}^{2}\right)-2 C_{n}(j, k)^{2}\right\}
\end{aligned}
$$

As a consequence, one deduces that

$$
\sum_{j, k=1}^{d} E\left[\left(C_{n}(j, k)-\frac{1}{q_{j}}\left\langle D F_{j, n}, D F_{k, n}\right\rangle_{\mathfrak{H}}\right)^{2}\right] \leqslant \Delta_{n} .
$$

Using Proposition 3.7, one infers immediately that

$$
\begin{equation*}
\tau_{F_{n}}^{j, k}(\mathbf{x}):=\frac{1}{q_{j}} E\left[\left\langle D F_{j, n}, D F_{k, n}\right\rangle_{\mathfrak{H}} \mid F_{n}=\mathbf{x}\right], \quad j, k=1, \ldots, d, \tag{4.77}
\end{equation*}
$$

defines a Stein's matrix for $F_{n}$, which moreover satisfies the relation

$$
\begin{equation*}
\sum_{j, k=1}^{d} E\left[\left(C(j, k)-\tau_{F_{n}}^{j, k}\left(F_{n}\right)\right)^{2}\right] \leqslant \Delta_{n} \tag{4.78}
\end{equation*}
$$

Now let $\Gamma_{n}$ denote the Malliavin matrix of $F_{n}$. Thanks to [43, Lemma 6], we know that, for any $i, j=1, \ldots, d$,

$$
\begin{equation*}
\left\langle D F_{i, n}, D F_{j, n}\right\rangle_{\mathfrak{H}} \xrightarrow{L^{2}(\sigma(\mathbf{G}))} \sqrt{q_{i} q_{j}} C(i, j) \quad \text { as } n \rightarrow \infty . \tag{4.79}
\end{equation*}
$$

Since $\left\langle D F_{i, n}, D F_{j, n}\right\rangle_{\mathfrak{H}}$ lives in a finite sum of chaoses (see e.g. [36, Chapter 5]) and is bounded in $L^{2}(\sigma(\mathbf{G}))$, we can again apply the hypercontractive estimate (3.64) to deduce that $\left\langle D F_{i, n}, D F_{j, n}\right\rangle_{\mathfrak{H}}$ is actually bounded in $L^{p}(\sigma(\mathbf{G}))$ for every $p \geqslant 1$, so that the convergence in (4.79) is in the sense of any of the spaces $L^{p}(\sigma(\mathbf{G}))$. As a consequence, $E\left[\operatorname{det} \Gamma_{n}\right] \rightarrow$ $\operatorname{det} C \prod_{i=1}^{d} q_{i}=: \gamma>0$, and there exists $n_{0}$ large enough so that

$$
\inf _{n \geqslant n_{0}} E\left[\operatorname{det} \Gamma_{n}\right]>0
$$

We are now able to deduce from Lemma 4.4 the existence of two constants $\kappa>0$ and $\alpha \in\left(0, \frac{1}{2}\right]$ such that, for all $\mathbf{x} \in \mathbb{R}^{d}, t \in\left[\frac{1}{2}, 1\right]$ and $n \geqslant n_{0}$,

$$
\mathbf{T V}\left(\sqrt{t} F_{n}+\sqrt{1-t} \mathbf{x}, F_{n}\right) \leqslant \kappa\left(1+\|\mathbf{x}\|_{1}\right)(1-t)^{\alpha}
$$

This means that relation (2.53) is satisfied uniformly on $n$. Concerning (2.52), again by hypercontractivity and using the representation (4.77), one has that, for all $\eta>0$,

$$
\sup _{n \geqslant 1} E\left[\left|\tau_{F_{n}}^{j, k}\left(F_{n}\right)\right|^{\eta+2}\right]<\infty, \quad j, k=1, \ldots, d .
$$

Finally, since $\Delta_{n} \rightarrow 0$ and because (4.78) holds true, the condition (2.54) is satisfied for $n$ large enough. The proof of (4.66) is concluded by applying Theorem 2.11.

### 4.4. Proof of Corollary 4.2

In view of Theorem 4.1, one has only to prove that (b) implies (a). This is an immediate consequence of the fact that the covariance $C_{n}$ converges to $C$, and that the sequence $\left\{F_{n}\right\}$ lives in a finite sum of Wiener chaoses. Indeed, by virtue of (3.64) one has that

$$
\sup _{n \geqslant 1} E\left[\left\|F_{n}\right\|^{p}\right]<\infty, \quad \forall p \geqslant 1,
$$

yielding in particular that, if $F_{n}$ converges in distribution to $Z$, then $E\left\|F_{n}\right\|^{4} \rightarrow E\|Z\|^{4}$ or, equivalently, $\Delta_{n} \rightarrow 0$. The proof is concluded.

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