

# Contents

<b>Jury</b>	<b>iii</b>
<b>Acknowledgements</b>	<b>v</b>
<b>Abstract</b>	<b>vii</b>
<b>Glossary</b>	<b>ix</b>
<b>1 Introduction</b>	<b>1</b>
1.1 Future telescopes . . . . .	1
1.1.1 Aperture . . . . .	1
1.1.2 Areal density and stowability for space applications . . . . .	6
1.1.3 High resolution with large Field of View (FoV) . . . . .	10
1.2 Active components in large telescopes . . . . .	12
1.2.1 Active Optics . . . . .	13
1.2.2 Adaptive Optics . . . . .	16
1.3 Control strategies for wavefront reconstruction . . . . .	21
1.3.1 Quasi-static control . . . . .	21
1.3.2 Dynamic control . . . . .	23
1.4 Outline . . . . .	23
1.5 References . . . . .	25
<b>2 Configuration study of piezoelectric space reflectors</b>	<b>29</b>
2.1 Introduction . . . . .	29
2.2 Mechanical behavior of adaptive thin shell . . . . .	32
2.2.1 Intrinsic stiffness of curved thin shell . . . . .	32
2.3 Pattern design scheme based on keystone layout . . . . .	39
2.4 Shape control with a large array of electrodes . . . . .	41
2.5 Petal design of large-scale parabolic reflector . . . . .	44
2.5.1 Motivation of petal configuration . . . . .	44
2.5.2 Comparative study in petal and full configuration design . . . . .	45

2.6	Conclusions . . . . .	47
2.7	References . . . . .	47
<b>3</b>	<b>Adaptive membrane mirrors: design, manufacturing and test</b>	<b>49</b>
3.1	Introduction . . . . .	49
3.2	Membrane mirror demonstrator . . . . .	51
3.2.1	Prototype design . . . . .	51
3.2.2	Composite membrane . . . . .	52
3.3	Poling treatment . . . . .	53
3.3.1	Electrical breakdown . . . . .	53
3.3.2	Experimental set-up . . . . .	55
3.4	Experiments on the composite membrane . . . . .	55
3.4.1	Estimate of piezoelectric coefficient . . . . .	55
3.4.2	Electrostrictive effect . . . . .	60
3.4.3	Actuation experiments . . . . .	60
3.5	Conclusions . . . . .	63
3.6	References . . . . .	65
<b>4</b>	<b>Control-structure interaction in piezoelectric deformable mirrors</b>	<b>67</b>
4.1	Introduction . . . . .	67
4.2	Feedback control of deformable mirrors . . . . .	68
4.2.1	Feedback control based on quasi-static model . . . . .	68
4.2.2	Mirror dynamics . . . . .	73
4.3	Control-structure interaction . . . . .	75
4.3.1	An Illustration on a SISO system . . . . .	75
4.3.2	Robustness test of MIMO system . . . . .	77
4.4	Damping augmentation strategies . . . . .	79
4.4.1	Passive damping with shunted circuit . . . . .	79
4.4.2	Active damping with modal filter . . . . .	81
4.5	Conclusions . . . . .	86
4.6	References . . . . .	86
<b>5</b>	<b>Field stabilization control of the E-ELT under wind disturbance</b>	<b>89</b>
5.1	Introduction . . . . .	89
5.2	Disturbance spectra . . . . .	91
5.2.1	Atmospheric tilt . . . . .	91
5.2.2	Wind disturbance spectra . . . . .	92
5.3	Feedback control of the tip-tilt mirror (TTM) . . . . .	94
5.3.1	Control-structure interaction model . . . . .	95
5.3.2	Stability analysis . . . . .	97
5.3.3	Disturbance rejection . . . . .	98

5.4	Response of the telescope structure . . . . .	104
5.4.1	Telescope model . . . . .	104
5.4.2	Stability analysis . . . . .	105
5.4.3	M1 response to M5 control torques . . . . .	108
5.5	Conclusion . . . . .	109
5.6	References . . . . .	110
<b>6</b>	<b>Conclusions</b>	<b>113</b>
<b>A</b>	<b>Optical background</b>	<b>119</b>
A.1	Wavefront aberration . . . . .	119
A.2	Zernike polynomials . . . . .	120
<b>B</b>	<b>Materials for polymer reflectors</b>	<b>125</b>
<b>C</b>	<b>Electrostrictive effect</b>	<b>129</b>
<b>D</b>	<b>Acceptance functions</b>	<b>133</b>
<b>E</b>	<b>Finite Element model of the E-ELT</b>	<b>137</b>