## Elliptical Multiple-Output Quantile Regression and Convex Optimization

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# Elliptical Multiple-Output Quantile Regression and Convex Optimization 

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#### Abstract

This article extends linear quantile regression to an elliptical multiple-output regression setup. The definition of the proposed concept leads to a convex optimization problem. Its elementary properties, and the consistency of its sample counterpart, are investigated. An empirical application is provided. Keywords: quantile regression, elliptical quantile, multivariate quantile, multiple-output regression


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## 1. Introduction

Due to their close relation to location and scatter, and their central role in the geometry of Gaussian and elliptical distributions, ellipsoids and the related Mahalanobis distances are quite logical tools for the statistical analysis of multivariate data. Quite naturally, thus, ellipsoids have been considered in the definition of multivariate quantiles and related concepts.

[^0]A definition of elliptical multivariate quantiles has been proposed by Hlubinka and Šiman (2013), which leads to a convex optimization problem, hence to a unique solution. That concept essentially deals with location, although its weighted version, based on covariate-driven weights, allows, in the presence of covariates, for a local constant regression extension. In the location case (when no covariates are available), Hlubinka and Šiman (2015) consider a more general nonlinear definition, leading to non-convex optimization. The uniqueness of the resulting quantile, therefore, is problematic.

This paper, inspired by Koenker and Bassett (1978), presents a linear multiple-output quantile regression extension of Hlubinka and Šiman (2013) and shows that it leads to a convex optimization problem with a uniquely defined solution for all multivariate continuous distributions with finite secondorder moments and connected support, including those with multimodal densities that often arise in the context of mixtures (see, e.g., Došlá (2009)).

Section 2 presents the new concept, Sections 3 and 4 investigate its main properties in the population case and in the sample case, and Section 5 briefly illustrates it with a real data application.

## 2. Definition

Let $\tau \in(0,1)$ and consider an $m$-dimensional response vector $\boldsymbol{Y}$ associated with a $(p+1)$-dimensional vector of regressors $\left(1, \boldsymbol{Z}^{\prime}\right)^{\prime}$. Throughout, it is assumed that the joint distribution of $\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime}$ is absolutely continuous, with connected support and finite second-order moments.

In the location case (when $p=0$ ), Hlubinka and Šiman (2013) define the
multivariate (location) elliptical $\tau$-quantile as the ellipsoid

$$
\varepsilon_{\tau}^{\mathrm{loc}}=\varepsilon_{\tau}^{\mathrm{loc}}(\boldsymbol{Y}):=\left\{\boldsymbol{y} \in \mathbb{R}^{m}: \boldsymbol{y}^{\prime} \mathbb{A}_{\tau} \boldsymbol{y}+\boldsymbol{y}^{\prime} \boldsymbol{b}_{\tau}-c_{\tau}=0\right\}
$$

where $\mathbb{A}_{\tau} \in \mathbb{R}^{m \times m}, \boldsymbol{b}_{\tau} \in \mathbb{R}^{m \times 1}$, and $c_{\tau}>0$ minimize, subject to $\mathbb{A}$ being symmetric and positive semidefinite with determinant one ( $\mathbb{A}$ is thus a shape matrix in the sense of Paindaveine (2008)), the objective function

$$
\Psi_{\tau}^{\mathrm{loc}}(\mathbb{A}, \boldsymbol{b}, c):=\mathrm{E} \rho_{\tau}\left(\boldsymbol{Y}^{\prime} \mathbb{A} \boldsymbol{Y}+\boldsymbol{Y}^{\prime} \boldsymbol{b}-c\right)
$$

with the usual check function $\rho_{\tau}(x):=x(\tau-\mathrm{I}(x<0))=\max \{(\tau-1) x, \tau x\}$. The positive semidefiniteness of $\mathbb{A}$ and the condition on its determinant ensure that $\varepsilon_{\tau}^{\text {loc }}$ is indeed an ellipsoid, centered at $\boldsymbol{s}_{\tau}:=-\mathbb{A}_{\tau}^{-1} \boldsymbol{b}_{\tau} / 2$, with equation $\left(\boldsymbol{y}-\boldsymbol{s}_{\tau}\right)^{\prime} \mathbb{A}_{\tau}\left(\boldsymbol{y}-\boldsymbol{s}_{\tau}\right)=\kappa_{\tau}$, where $\kappa_{\tau}:=c_{\tau}+\boldsymbol{b}_{\tau}^{\prime} \mathbb{A}_{\tau}^{-1} \boldsymbol{b}_{\tau} / 4$. The condition $\operatorname{det}(\mathbb{A})=1$ can be viewed as an identification constraint: for any $K>0$, the triples $(\mathbb{A}, \boldsymbol{b}, c)$ and $(K \mathbb{A}, K \boldsymbol{b}, K c)$ indeed define the same ellipsoid.

The same definition can be reformulated as a convex optimization problem by relaxing the constraint $\operatorname{det}(\mathbb{A})=1$ into $(\operatorname{det}(\mathbb{A}))^{1 / m} \geq 1$ : the function $\mathbb{A} \mapsto(\operatorname{det}(\mathbb{A}))^{1 / m}$, unlike $\mathbb{A} \mapsto \operatorname{det}(\mathbb{A})$, is concave on the cone of symmetric positive semidefinite matrices (see, e.g., Šilhavý (2015)), and the fact that $\Psi_{\tau}^{\text {loc }}(K \mathbb{A}, K \boldsymbol{b}, K c)=K \Psi_{\tau}^{\text {loc }}(\mathbb{A}, \boldsymbol{b}, c)$ for any $K>0$ implies that the optimal $\mathbb{A}_{\tau}$ is such that $\left(\operatorname{det}\left(\mathbb{A}_{\tau}\right)\right)^{1 / m}=\operatorname{det}\left(\mathbb{A}_{\tau}\right)=1$ (see Section 2 of Hlubinka and Šiman (2013), where alternative identification constraints are also discussed).

In the presence of covariates (that is, when $p \geq 1$ ), the traditional homoscedastic multiple-output linear regression model suggests, for an elliptical multiple-output regression $\tau$-quantile, a simple equation of the form

$$
(\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})^{\prime} \mathbb{A}_{\tau}(\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})-\gamma=0
$$

with some $\mathbb{A} \in \mathbb{R}^{m \times m}, \boldsymbol{\beta} \in \mathbb{R}^{m \times 1}, \mathbb{B} \in \mathbb{R}^{m \times p}$, and $\gamma>0$. The trouble is that the corresponding objective function

$$
\mathrm{E} \rho_{\tau}\left((\boldsymbol{Y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{Z})^{\prime} \mathbb{A}(\boldsymbol{Y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{Z})-\gamma\right)
$$

$\varepsilon_{\tau}^{\mathrm{reg}}:=\left\{\left(\boldsymbol{y}^{\prime}, \boldsymbol{z}^{\prime}\right)^{\prime} \in \mathbb{R}^{m+p}:\left(\boldsymbol{y}-\boldsymbol{\beta}_{\tau}-\mathbb{B}_{\tau} \boldsymbol{z}\right)^{\prime} \mathbb{A}_{\tau}\left(\boldsymbol{y}-\boldsymbol{\beta}_{\tau}-\mathbb{B}_{\tau} \boldsymbol{z}\right)-\left(\gamma_{\tau}+\boldsymbol{c}_{\tau}^{\prime} \boldsymbol{z}+\boldsymbol{z}^{\prime} \mathbb{C} \boldsymbol{z}\right)=0\right\}$
of an elliptical regression quantile $\varepsilon_{\tau}^{\mathrm{reg}}=\varepsilon_{\tau}^{\mathrm{reg}}(\boldsymbol{Y}, \boldsymbol{Z})$, where a quadratic form of covariate-driven scale is allowed, and $\mathbb{A}_{\tau}, \boldsymbol{\beta}_{\tau}, \mathbb{B}_{\tau}, \gamma_{\tau}, \boldsymbol{c}_{\tau}$, and $\mathbb{C}_{\tau}$ jointly minimize

$$
\Psi_{\tau}^{\mathrm{reg}}:=\mathrm{E} \rho_{\tau}\left((\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})^{\prime} \mathbb{A}(\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})-\left(\gamma+\boldsymbol{c}^{\prime} \boldsymbol{z}+\boldsymbol{z}^{\prime} \mathbb{C} \boldsymbol{z}\right)\right)
$$

under the constraint that $\mathbb{C} \in \mathbb{R}^{p \times p}$ is symmetric and $\mathbb{A} \in \mathbb{R}^{m \times m}$ is symmetric positive semidefinite with $\operatorname{det}(\mathbb{A})=1$. This minimization, however, still does not take the form of a convex optimization problem.

Let therefore $\mathbb{M}:=\left(\mathbb{M}^{1}, \ldots, \mathbb{M}^{6}\right)$, with $\mathbb{M}^{1}:=\mathbb{A} \in \mathbb{R}^{m \times m}$ symmetric positive semidefinite, $\mathbb{M}^{2}:=\mathbb{B}^{\prime} \mathbb{A} \mathbb{B}-\mathbb{C} \in \mathbb{R}^{p \times p}$ symmetric, $\mathbb{M}^{3}:=-2 \mathbb{B}^{\prime} \mathbb{A} \in \mathbb{R}^{p \times m}$, $\mathbb{M}^{4}:=-2 \boldsymbol{\beta}^{\prime} \mathbb{A} \in \mathbb{R}^{1 \times m}, \mathbb{M}^{5}:=2 \boldsymbol{\beta}^{\prime} \mathbb{A B}-\boldsymbol{c}^{\prime} \in \mathbb{R}^{1 \times p}$, and $\mathbb{M}^{6}:=\boldsymbol{\beta}^{\prime} \mathbb{A} \boldsymbol{\beta}-\gamma \in \mathbb{R}$. The correspondence between $\mathbb{M}$ and $(\mathbb{A}, \boldsymbol{\beta}, \mathbb{B}, \gamma, \boldsymbol{c}, \mathbb{C})$ is one-to-one, with $\mathbb{A}=\mathbb{M}^{1}, \boldsymbol{\beta}=-\frac{1}{2} \mathbb{M}^{1^{-1}} \mathbb{M}^{4^{\prime}}, \quad \mathbb{B}=-\frac{1}{2} \mathbb{M}^{1-1} \mathbb{M}^{3 \prime}, \gamma=\frac{1}{4} \mathbb{M}^{4} \mathbb{M}^{1-1} \mathbb{M}^{4^{\prime}}-\mathbb{M}^{6}$, $\boldsymbol{c}=\frac{1}{2} \mathbb{M}^{3} \mathbb{M}^{1-1} \mathbb{M}^{4}-\mathbb{M}^{5^{\prime}}$, and $\mathbb{C}=\frac{1}{4} \mathbb{M}^{3} \mathbb{M}^{1^{-1}} \mathbb{M}^{3 \prime}-\mathbb{M}^{2}: \mathbb{M}$ thus provides a reparametrization of the problem.

In this new parametrization, the elliptical regression quantile $\varepsilon_{\tau}^{\mathrm{reg}}$ can be expressed as

$$
\varepsilon_{\tau}^{\mathrm{reg}}=\left\{\left(\boldsymbol{y}^{\prime}, \boldsymbol{z}^{\prime}\right)^{\prime} \in \mathbb{R}^{m+p}: r\left(\boldsymbol{y}, \boldsymbol{z}, \mathbb{M}_{\tau}\right)=0\right\}
$$

where

$$
\begin{aligned}
r(\boldsymbol{y}, \boldsymbol{z}, \mathbb{M}) & :=\boldsymbol{y}^{\prime} \mathbb{M}^{1} \boldsymbol{y}+\boldsymbol{z}^{\prime} \mathbb{M}^{2} \boldsymbol{z}+\boldsymbol{z}^{\prime} \mathbb{M}^{3} \boldsymbol{y}+\mathbb{M}^{4} \boldsymbol{y}+\mathbb{M}^{5} \boldsymbol{z}+\mathbb{M}^{6} \\
& =(\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})^{\prime} \mathbb{A}(\boldsymbol{y}-\boldsymbol{\beta}-\mathbb{B} \boldsymbol{z})-\left(\gamma+\boldsymbol{c}^{\prime} \boldsymbol{z}+\boldsymbol{z}^{\prime} \mathbb{C} \boldsymbol{z}\right)
\end{aligned}
$$

and $\mathbb{M}_{\tau}:=\left(\mathbb{M}_{\tau}^{1}, \ldots, \mathbb{M}_{\tau}^{6}\right)$ jointly minimize

$$
\Psi_{\tau}^{\mathrm{reg}}=\Psi_{\tau}^{\mathrm{reg}}(\mathbb{M}):=\Psi_{\tau}^{\mathrm{reg}}\left(\mathbb{M}^{1}, \ldots, \mathbb{M}^{6}\right)=\mathrm{E} \rho_{\tau}(r(\boldsymbol{Y}, \boldsymbol{Z}, \mathbb{M}))
$$

subject to $\left(\operatorname{det}\left(\mathbb{M}^{1}\right)\right)^{1 / m} \geq 1$. As in the location case, positive homogeneity of $\Psi_{\tau}^{\text {reg }}\left(\mathbb{M}^{1}, \ldots, \mathbb{M}^{6}\right)$ implies $\operatorname{det}\left(\mathbb{M}_{\tau}\right)=1$. The considerable advantage of the parametrization in terms of $\mathbb{M}$ is that it leads to a convex optimization problem, hence to a unique minimum under the assumptions made.

In principle, one might place further convex constraints on the parameters $\mathbb{M}^{1}, \ldots, \mathbb{M}^{6}$ in order to simplify the model, such as

$$
\begin{aligned}
\mathbb{M}^{3}=0 & \Longleftrightarrow \mathbb{B}=0, \\
\mathbb{M}^{2}=0 \text { and } \mathbb{M}^{3}=0 & \Longleftrightarrow \mathbb{B}=0 \text { and } \mathbb{C}=0, \\
\mathbb{M}^{3}=0 \text { and } \mathbb{M}^{5}=0 & \Longleftrightarrow \mathbb{B}=0 \text { and } \boldsymbol{c}=0, \\
\mathbb{M}^{2}=0, \mathbb{M}^{3}=0, \text { and } \mathbb{M}^{5}=0 & \Longleftrightarrow \mathbb{B}=0, \mathbb{C}=0, \text { and } \boldsymbol{c}=0 ;
\end{aligned}
$$

the resulting optimization problems still are convex, hence also lead to uniquely defined elliptical regression quantiles. In particular, the last set of constraints corresponds to the location elliptical quantiles of Hlubinka and Šiman (2013) which, therefore, are included as a special case. Other natural constraints
and

$$
\begin{equation*}
\frac{L_{\tau}}{m \tau(1-\tau)} \operatorname{det}\left(\mathbb{M}_{\tau}^{1}\right)^{1 / m} \mathbb{M}_{\tau}^{1-1}=\frac{1}{1-\tau} \mathrm{E}\left[\boldsymbol{Y} \boldsymbol{Y}^{\prime} \mathrm{I}_{[r \geq 0]}\right]-\frac{1}{\tau} \mathrm{E}\left[\boldsymbol{Y} \boldsymbol{Y}^{\prime} \mathrm{I}_{[r<0]}\right] \tag{8}
\end{equation*}
$$

where $r=r\left(\boldsymbol{Y}, \boldsymbol{Z}, \mathbb{M}_{\tau}\right)$ and $L_{\tau}$ is the Lagrange multiplier associated with the determinant-based constraint $\left(\operatorname{det}\left(\mathbb{M}^{1}\right)\right)^{1 / m} \geq 1$ (recall that $\mathbb{M}^{1}$ is assumed

## function.

Conditions (2)-(8) are easy to interpret: (2) only scales the problem; (3) provides $\varepsilon_{\tau}^{\text {reg }}$ with a clear probability interpretation, namely, that its probability content is $\tau$; (4) and (5) further imply that

$$
\mathrm{E}\left[\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime} \mid r \geq 0\right]=\mathrm{E}\left[\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime} \mid r<0\right]
$$

so that the probability mass centers of the interior of $\varepsilon_{\tau}^{\text {reg }}$ and the exterior of $\varepsilon_{\tau}^{\mathrm{reg}}$ coincide; conditions (6)-(8) yield

$$
\left(\begin{array}{cc}
L_{\tau} \frac{1}{m \tau(1-\tau)} \mathbb{M}_{\tau}^{1-1} & 0 \\
0 & 0
\end{array}\right)=\operatorname{var}\left(\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime} \mid r \geq 0\right)-\operatorname{var}\left(\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime} \mid r<0\right)
$$

which relates $\left(\mathbb{M}_{\tau}^{1}\right)^{-1}$ to the difference between the "inner" and "outer" (conditional) variances. Due to an unfortunate typo, the same formula for the location case is repeatedly stated without the $\tau(1-\tau)$ factor in Hlubinka and Šiman (2013), namely in Part [4] of Theorem 2 and in the text preceding it.

It is easy to see that the elliptical regression quantiles $\varepsilon_{\tau}^{\text {reg }}$ are both regression-equivariant and fully affine-equivariant: if $\boldsymbol{f} \in \mathbb{R}^{m \times 1}, \mathbb{F} \in \mathbb{R}^{m \times m}$, $\mathbb{G} \in \mathbb{R}^{m \times p}, \mathbb{H} \in \mathbb{R}^{p \times p}, d=\operatorname{det}(\mathbb{F})$, and $\varepsilon_{\tau}^{\text {reg }}(\boldsymbol{Y}, \boldsymbol{Z})$ of (1) leads to quantile coefficients $\mathbb{A}_{\tau}, \boldsymbol{\beta}_{\tau}, \mathbb{B}_{\tau}, \gamma_{\tau}, \boldsymbol{c}_{\tau}$, and $\mathbb{C}_{\tau}$, then $\varepsilon_{\tau}^{\mathrm{reg}}(\boldsymbol{Y}+\boldsymbol{f}+\mathbb{G} \boldsymbol{Z}, \boldsymbol{Z})$ leads to $\mathbb{A}_{\tau}$, $\boldsymbol{\beta}_{\tau}+\boldsymbol{f}, \mathbb{B}_{\tau}+\mathbb{G}, \gamma_{\tau}, \boldsymbol{c}_{\tau}$, and $\mathbb{C}_{\tau}$, and $\varepsilon_{\tau}^{\mathrm{reg}}(\boldsymbol{f}+\mathbb{F} \boldsymbol{Y}, \mathbb{H} \boldsymbol{Z})$ leads to $d^{2}\left(\mathbb{F}^{-1}\right)^{\prime} \mathbb{A}_{\tau} \mathbb{F}^{-1}$, $\boldsymbol{\beta}_{\tau}+\boldsymbol{f}, \mathbb{B}_{\tau} \mathbb{H}^{-1}, d^{2} \gamma_{\tau}, d^{2}\left(\mathbb{H}^{-1}\right)^{\prime} \boldsymbol{c}_{\tau}$, and $d^{2}\left(\mathbb{H}^{-1}\right)^{\prime} \mathbb{C}_{\tau} \mathbb{H}^{-1}$.

## 4. Main properties: sample case

In the sample case with $n$ observations $\left(\boldsymbol{Y}_{i}^{\prime}, \boldsymbol{Z}_{i}^{\prime}\right)^{\prime}, i=1, \ldots, n$, empirical versions $\varepsilon_{\tau ; n}^{\mathrm{reg}}$ of the elliptical regression quantiles $\varepsilon_{\tau}^{\mathrm{reg}}$ can be defined by considering expectations with respect to empirical distributions. It makes sense, however, to consider here a slightly more general weighted setup with a positive weight $w_{i}$ associated with the $i$ th observation, $i=1, \ldots, n$. Those weights can be useful for implementing bootstrap or for handling ties. The weighted optimization problem may then be rewritten as

$$
\min _{\mathbb{M}^{1}, \ldots, \mathbb{M}^{6}, \boldsymbol{r}^{+}, \boldsymbol{r}^{-}} \Psi_{\tau ; n}^{\mathrm{reg}}(\mathbb{M}):=\sum_{i=1}^{n} \tau w_{i} r_{i}^{+}+\sum_{i=1}^{n}(1-\tau) w_{i} r_{i}^{-}
$$

subject to the (differentiable) feasibility constraints

$$
\begin{align*}
& -\operatorname{det}\left(\mathbb{M}^{1}\right)^{1 / m}+1 \leq 0, \quad-r_{i}^{+} \leq 0 \quad \text { and } \quad-r_{i}^{-} \leq 0, \quad i=1, \ldots, n,  \tag{9}\\
& r\left(\boldsymbol{Y}_{i}, \boldsymbol{Z}_{i}, \mathbb{M}\right)-r_{i}^{+}+r_{i}^{-}=0, \quad i=1, \ldots, n,  \tag{10}\\
& \mathbb{M}^{1} \text { is a symmetric positive semidefinite matrix, }  \tag{11}\\
& \mathbb{M}^{2} \text { is a symmetric matrix, } \tag{12}
\end{align*}
$$

where $r_{i}^{+}$and $r_{i}^{-}$are the positive and negative parts of the residual $r_{i}=$ $r_{i}^{+}-r_{i}^{-}:=r\left(\boldsymbol{Y}_{i}, \boldsymbol{Z}_{i}, \mathbb{M}\right), i=1, \ldots, n$.

As in Hlubinka and Šiman (2013), one can invoke the theory of convex optimization as exposed in Boyd and Vandenberghe (2004), check the refined Slater's constraint qualification, and apply the (Karush-)Kuhn-Tucker such that
the constraints (9)-(12) are satisfied for $\mathbb{M}_{\tau ; n}^{1}, \ldots, \mathbb{M}_{\tau ; n}^{6}$,

$$
\begin{equation*}
L\left(-\operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{1 / m}+1\right)=0 \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
\lambda_{i}^{+} r_{i}^{+}=0 \text { and } \lambda_{i}^{-} r_{i}^{-}=0, \quad i=1, \ldots, n \tag{14}
\end{equation*}
$$

$$
\begin{equation*}
w_{i} \tau-\lambda_{i}^{+}-\nu_{i}=0 \text { and } w_{i}(1-\tau)-\lambda_{i}^{-}+\nu_{i}=0, \quad i=1, \ldots, n \tag{15}
\end{equation*}
$$

$$
\begin{equation*}
\sum_{i=1}^{n} \nu_{i}=0, \quad \sum_{i=1}^{n} \nu_{i} \boldsymbol{Z}_{i}=0, \quad \text { and } \quad \sum_{i=1}^{n} \nu_{i} \boldsymbol{Y}_{i}=0 \tag{16}
\end{equation*}
$$

This implies $\lambda_{i}^{+}=0$ and $\nu_{i}=w_{i} \tau$ for $r_{i}^{+}>0, \lambda_{i}^{-}=0$ and $\nu_{i}=w_{i}(\tau-1)$ for $r_{i}^{-}>0$, and $w_{i}(\tau-1) \leq \nu_{i} \leq w_{i} \tau$ for $r_{i}=0$. Furthermore,

$$
\sum_{i=1}^{n} w_{i} \mathrm{I}_{\left[r_{i}<0\right]} \leq n \tau \leq \sum_{i=1}^{n} w_{i} \mathrm{I}_{\left[r_{i} \leq 0\right]}
$$

conditions. The matrices $\mathbb{M}_{\tau ; n}^{1}, \ldots, \mathbb{M}_{\tau ; n}^{6}$ thus solve the sample elliptical $\tau$ quantile optimization problem if and only if there exist $r_{i}^{+} \geq 0$ and $r_{i}^{-} \geq 0$, $i=1, \ldots, n$, and dual variables $L \geq 0, \lambda_{i}^{+} \geq 0, \lambda_{i}^{-} \geq 0$, and $\nu_{i}, i=1, \ldots, n$,

$$
\begin{equation*}
\sum_{i=1}^{n} \nu_{i} \boldsymbol{Z}_{i} \boldsymbol{Y}_{i}^{\prime}=0, \quad \sum_{i=1}^{n} \nu_{i} \boldsymbol{Z}_{i} \boldsymbol{Z}_{i}^{\prime}=0, \text { and } \tag{17}
\end{equation*}
$$

$$
\begin{equation*}
\sum_{i=1}^{n} \nu_{i} \boldsymbol{Y}_{i} \boldsymbol{Y}_{i}^{\prime}=\frac{L}{m} \operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{1 / m}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{-1} \tag{18}
\end{equation*}
$$

Up to the small deviations caused by the data points with zero residuals, the necessary and sufficient conditions (13)-(19) roughly can be interpreted as the sample counterparts of the population conditions (2)-(8).

The strong duality theorem for convex optimization implies that, for the
optimal solution $\mathbb{M}_{\tau ; n}:=\left(\mathbb{M}_{\tau ; n}^{1}, \ldots, \mathbb{M}_{\tau ; n}^{6}\right)$,

$$
\begin{aligned}
\Psi_{\tau ; n}^{\mathrm{reg}}\left(\mathbb{M}_{\tau ; n}\right)= & \tau \sum w_{i} r_{i}^{+}+(1-\tau) \sum w_{i} r_{i}^{-}+\sum \lambda_{i}\left(-r_{i}^{+}\right)+\sum \lambda_{i}\left(-r_{i}^{-}\right) \\
& +L\left(-\operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{1 / m}+1\right)+\sum \nu_{i}\left(r\left(\boldsymbol{Y}_{i}, \boldsymbol{Z}_{i}, \mathbb{M}_{\tau ; n}\right)-r_{i}^{+}+r_{i}^{-}\right) \\
= & \sum r_{i}^{+}\left(w_{i} \tau-\lambda_{i}-\nu_{i}\right)+\sum r_{i}^{-}\left(w_{i}(1-\tau)-\lambda_{i}+\nu_{i}\right)+0 \\
& +\mathbb{M}_{\tau ; n}^{6}\left(\sum \nu_{i}\right)+\mathbb{M}_{\tau ; n}^{5}\left(\sum \nu_{i} \boldsymbol{Z}_{i}\right)+\mathbb{M}_{\tau ; n}^{4}\left(\sum \nu_{i} \boldsymbol{Y}_{i}\right) \\
& +\operatorname{tr}\left(\mathbb{M}_{\tau ; n}^{3} \sum \nu_{i} \boldsymbol{Y}_{i} \boldsymbol{Z}_{i}^{\prime}\right)+\operatorname{tr}\left(\mathbb{M}_{\tau ; n}^{2} \sum \nu_{i} \boldsymbol{Z}_{i} \boldsymbol{Z}_{i}^{\prime}\right)+\operatorname{tr}\left(\mathbb{M}_{\tau ; n}^{1} \sum \nu_{i} \boldsymbol{Y}_{i} \boldsymbol{Y}_{i}^{\prime}\right) \\
= & L \operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{1 / m} \operatorname{tr}\left(\mathbb{M}_{\tau ; n}^{1} \mathbb{M}_{\tau ; n}^{1}{ }^{-1}\right) / m=L \operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{1 / m},
\end{aligned}
$$

where all sums run from $i=1$ to $n$. If $\Psi_{\tau ; n}^{\mathrm{reg}}=\Psi_{\tau ; n}^{\mathrm{reg}}\left(\mathbb{M}_{\tau ; n}^{1}, \ldots, \mathbb{M}_{\tau ; n}^{6}\right)>0$, then $L>0, \operatorname{det}\left(\mathbb{M}_{\tau ; n}^{1}\right)=1$, and $\Psi_{\tau ; n}^{\mathrm{reg}}=L$. If $\Psi_{\tau ; n}^{\mathrm{reg}}=0$, then necessarily $L=0$. In both cases,

$$
\Psi_{\tau ; n}^{\mathrm{reg}}\left(\mathbb{M}_{\tau ; n}^{1}, \ldots, \mathbb{M}_{\tau ; n}^{6}\right)=L
$$

and the optimal value of the objective function again equals that of the Lagrange multiplier associated with the determinant-based constraint.

All statements so far in this section are valid without any assumption at all. There are typically $p(p+1) / 2+p m+p+m+1$ zero residuals for all but a finite number of $\tau$ values if $n$ is sufficiently large, except for some very special data configurations that can be ruled out almost surely under the absolute continuity assumption on the underlying population distribution. Consequently, the number of distinct sample elliptical regression $\tau$-quantiles, $\tau \in(0,1)$, is finite and, for low $n$ and large $p$, relatively small.

If $w_{i}:=w\left(\boldsymbol{Y}_{i}, \boldsymbol{Z}_{i}\right)$, where $w$ is a square-integrable density positive on the same domain as the population density of $\left(\boldsymbol{Y}^{\prime}, \boldsymbol{Z}^{\prime}\right)^{\prime}$, then Theorem 5.14 of van der Vaart (1998) guarantees basic convergence, for $n \rightarrow \infty$, of the
(weighted) sample elliptical regression quantile coefficient vector

$$
\boldsymbol{m}_{\tau ; n}:=\left(\operatorname{vec}\left(\mathbb{M}_{\tau ; n}^{1}\right)^{\prime}, \operatorname{vec}\left(\mathbb{M}_{\tau ; n}^{2}\right)^{\prime}, \operatorname{vec}\left(\mathbb{M}_{\tau ; n}^{3}\right)^{\prime}, \mathbb{M}_{\tau ; n}^{4}, \mathbb{M}_{\tau ; n}^{5}, \mathbb{M}_{\tau ; n}^{6}\right)^{\prime}
$$

to its (uniquely defined) population counterpart

$$
\boldsymbol{m}_{\tau}:=\left(\operatorname{vec}\left(\mathbb{M}_{\tau}^{1}\right)^{\prime}, \operatorname{vec}\left(\mathbb{M}_{\tau}^{2}\right)^{\prime}, \operatorname{vec}\left(\mathbb{M}_{\tau}^{3}\right)^{\prime}, \mathbb{M}_{\tau}^{4}, \mathbb{M}_{\tau}^{5}, \mathbb{M}_{\tau}^{6}\right)^{\prime}
$$

in the sense that

$$
\mathrm{P}\left(\left\{\left\|\boldsymbol{m}_{\tau ; n}-\boldsymbol{m}_{\tau}\right\|>\varepsilon\right\} \text { and }\left\{\boldsymbol{m}_{\tau ; n} \in \mathcal{K}\right\}\right) \longrightarrow_{n \rightarrow \infty} 0
$$

for any $\varepsilon>0$ and any compact set $\mathcal{K}$ of the right dimension. The location version of this result for unit weights in Theorem 3 of Hlubinka and Šiman (2013) is stated incorrectly with the $\notin$ symbol instead of $\in$.

The optimization (semidefinite programming) behind the sample weighted elliptical regression quantiles can be done, e.g., with the CVX toolbox (Grant and Boyd, 2008, 2009) for MATLAB (The MathWorks, Inc., 2013), that can handle relatively large and multi-dimensional datasets.

## 5. A real-data example

The theory shows that elliptical regression quantiles are particularly suitable for large datasets without outliers. In this section, they are computed for body girth measurements data (Heinz et al., 2003) that are often used for illustrating various statistical methods, despite the fact that they do not constitute a random sample from any well-defined population.

In this example, $n=260$ observations of calf maximum girth $Y_{1}(\mathrm{~cm})$ and thigh maximum girth $Y_{2}(\mathrm{~cm})$ of physically active women are modeled
with the aid of a single regressor $Z$ representing either their body mass index (BMI) or their age. Figure 1 displays the sample version of $\varepsilon_{\tau}^{\mathrm{reg}}\left(\left(\boldsymbol{Y}_{1}^{\prime}, \boldsymbol{Y}_{2}^{\prime}\right)^{\prime}, \boldsymbol{z}_{0}\right)$ for $\tau \approx 0.032,0.560$, and $0.933^{1}$ at some empirical quantiles (of orders 0.1, $0.3,0.5,0.7$, and 0.9 ) of the regressor $Z$. The figure clearly reveals different but meaningful trends and heteroskedasticity patterns for different quantile levels. Interested readers may compare these results with those obtained for the same data by the competing methods of Hallin et al. (2010, 2015).

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Figure 1: Application to the body girth measurement data. The figure illustrates the dependence of calf maximum girth $Y_{1}$ (in cm ) and thigh maximum girth $Y_{2}$ (in cm ) on a single regressor $Z$, which is either the body mass index (left) or age (right), by means of the empirical parametric elliptical regression quantiles $\varepsilon_{\tau ; n}^{\text {reg }}\left(\left(Y_{1}, Y_{2}\right)^{\prime}, z_{0}\right)$ obtained from $n=260$ observations for $\tau \approx 0.032,0.560$, and 0.933 and for $z_{0}$ equal to the empirical $p$ th quantile of $Z, p=0.1$ (black), 0.3 (blue), 0.5 (green), 0.7 (cyan), and 0.9 (yellow). The colors are visible only in the online version of the article.

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[^1]:    ${ }^{1}$ In the population case, those $\tau$-quantiles would match the location halfspace depth contours of a bivariate normal distribution at levels $0.40,0.10$, and 0.01 , respectively.

